

FM1125 User Manual

v1.6



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1 INTRODUCTION

1.1 Attention



Do not disassemble the device. If the device is damaged, the power supply cables are not isolated or the isolation is damaged, before unplugging the power supply, do not touch the device.



All wireless data transferring devices produce interference that may affect other devices which are placed nearby.



The device must be connected only by qualified personnel.



The device must be firmly fastened in the predefined location.



The programming must be performed using a second class PC (with autonomic power supply).



The device is susceptible to water and humidity.



Any installation and/or handling during a lightning storm are prohibited.



FM1125 has USB interface;
Please use cables provided with FM1125 device.
Teltonika is not responsible for any harm caused by using wrong cables for PC <-> FM1125 connection.

1.2 Instructions of safety

This chapter contains information on how to operate FM1125 safely. By following these requirements and recommendations, you will avoid dangerous situations. You must read these instructions carefully and follow them strictly before operating the device!

The device uses a 10 V...30 V DC power supply. The nominal voltage is 12 V DC. The allowed range of voltage is 10 V...30 V DC.

To avoid mechanical damage, it is advised to transport the FM1125 device in an impact-proof package. Before usage, the device should be placed so that its LED indicators are visible, which show the status of operation the device is in.

When connecting the connection (2x5) cables to the vehicle, the appropriate jumpers of the power supply of the vehicle should be disconnected.

Before dismounting the device from the vehicle, the 2x5 connection must be disconnected.

The device is designed to be mounted in a zone of limited access, which is inaccessible for the operator. All related devices must meet the requirements of standard EN 60950-1.

The device FM1125 is not designed as a navigational device for boats.

1.3 Legal Notice

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1.4 About document

This document contains information about the architecture, possibilities, mechanical characteristics, and configuration of the FM1125 device.

Acronyms and terms used in document

PC – Personal Computer.

GPRS – General Packet Radio Service

GPS – Global Positioning System

GSM – Global System for Mobile Communications

SMS – Short Message Service

AC/DC – Alternating Current/Direct Current

I/O – Input/Output

Record – AVL data stored in FM1125 memory. AVL data contains GPS and I/O information

AVL packet - data packet that is being sent to server during data transmission. AVL packet contains from 1 to 50 records.

2 BASIC DESCRIPTION

FM1125 is a terminal with GPS and GSM connectivity, which is able to determine the object's coordinates and transfer them via the GSM network. This device is perfectly suitable for applications, which need location acquirement of remote objects. It is important to mention that FM1125 has additional inputs and outputs, which let you control and monitor other devices on remote objects. FM1125 also has a USB port for device status log output and entering configurations.

2.1 Package contents¹

The FM1125 device is supplied to the customer in a cardboard box containing all the equipment that is necessary for operation. The package contains:

FM1125 device;

Input and output power supply cable with a 2x5 connection pins;

¹ Package content depends on Order Code, and can be customized by customer needs.

USB cable;

A card containing URL to download FM1125 device drivers and Configurator software.

170mAh Li-ion rechargeable 3,7V battery

2.2 Basic characteristics

GSM / GPRS features:

- Teltonika TM11Q quad band module (GSM 850 / 900 / 1800 / 1900 MHz);
- GPRS class 10;
- SMS (text, data).

GNSS features:

- TG3300 32 channel (or equivalent) receiver;
- Up to -161 dBm sensitivity.

Hardware features:

- Cortex®-M3 processor;
- 16 MB internal Flash memory;
- Built-in accelerometer.
- 170mAh Li-ion rechargeable 3,7V battery

Interface features:

- Power supply: 10 ÷ 30V;
- Internal/External GPS/GLONASS antenna;
- USB port;
- 1 digital inputs;
- 1 analog input;
- 1 open collector digital outputs;
- 1Wire® temperature sensor
- 1Wire® iButton
- LEDs indicating device status.
- 1 RS-232 , 1 RS-485 interfaces.

Special features:

- Any element event triggers (external sensor, input, speed, temperature, etc.);
- Highly configurable data acquisition and sending;
- Multiple Geo-fence areas;
- Sleep mode;
- Deep sleep mode;
- Configurable scenarios available;
- Real-time process monitoring;
- Authorized number list for remote access;
- Firmware update over GPRS or USB port;
- Configuration update over GPRS, SMS or USB port;
- TCP/IP or UDP/IP protocol support;
- 50000 record storing.

Overvoltage protection :

| Description | Voltage | Duration |
|--|---------|----------------|
| Normal operation | 10-30V | Unlimited |
| Protection turns on, device turns off. | 34V | Unlimited |
| Maximum voltage | <70V | Unlimited |
| Maximum voltage impulse | 90V | 5 mili seconds |

2.3 Technical features

| Part name | Physical specification | Technical details |
|----------------|---|---|
| Navigation LED | LED | Power supply 10...30 V DC 2W Max Energy consumption ¹ : GPRS: --- 120 mA r.m.s Max., Nominal: --- average 65 mA r.m.s, GPS Sleep: --- average 28 mA, Deep Sleep: --- average less than 7 mA ² Battery charge current: --- average 100 mA, Operation temperature: -25°C ... +55°C Storage temperature: -40°C ... +70°C Storage relative humidity 5 ... 95 % (no condensation) |
| Modem LED | LED | |
| Socket 2x5 | Tyco Micro MATE-N-LOK™ 4-794628-0 or similar | |
| USB | Mini USB socket | |

Table 1. FM1125 specifications

¹ Energy consumption has been tested at 12V voltage with no battery charging.

² When in Deep Sleep mode no data storing and sending is activated.

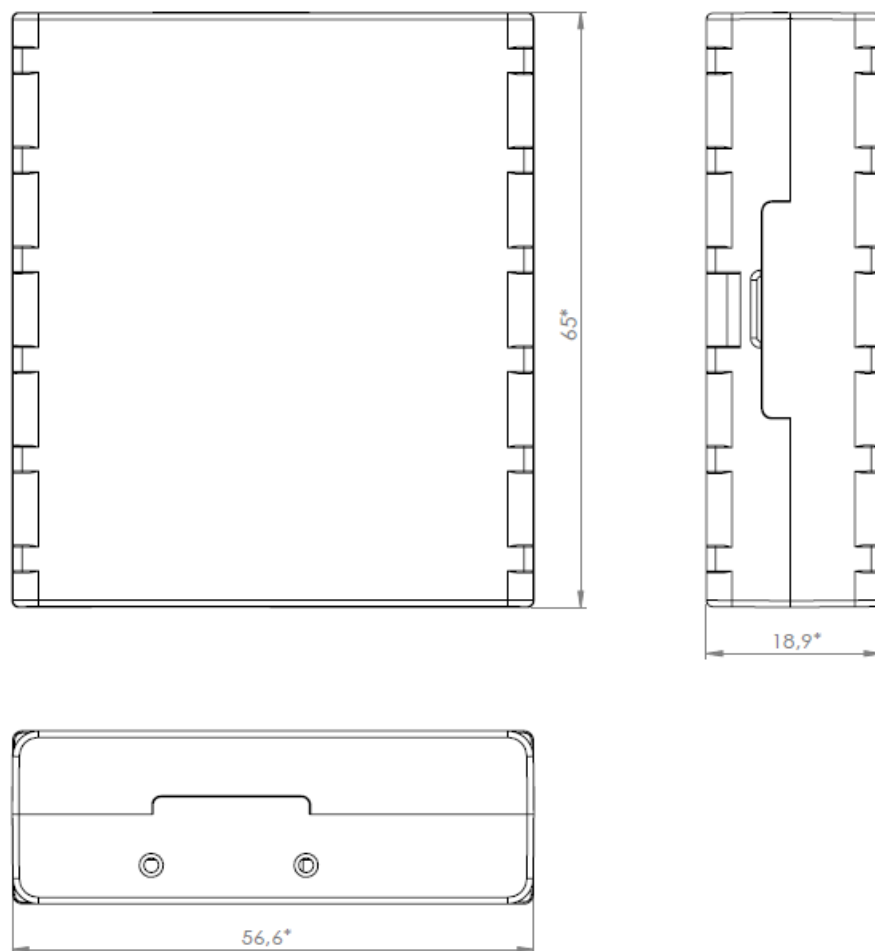


Figure 1 FM1125 with internal antenna view & dimensions (tolerance $\pm 2\text{mm}$)

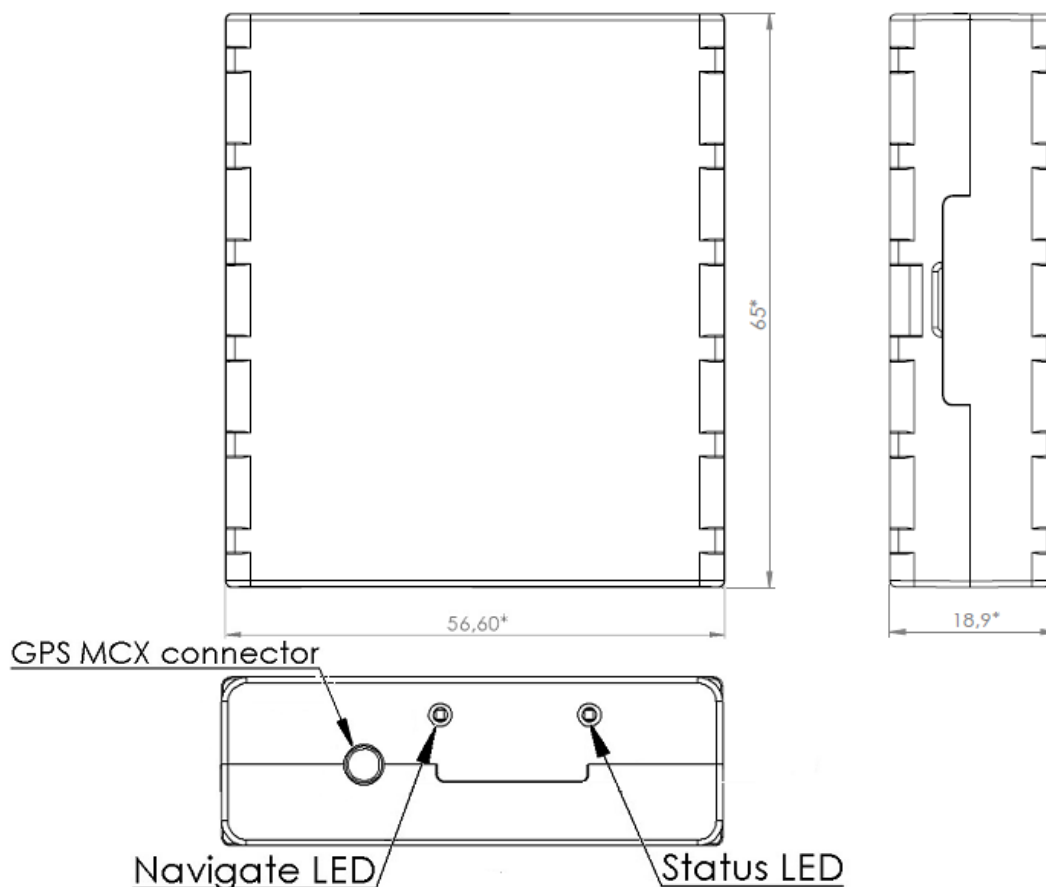


Figure 2 FM1125 with external antenna view & dimensions (tolerance $\pm 2\text{mm}$)

2.4 Technical Information about internal battery

Li-Polymer rechargeable battery, 3.7V, 170 mAh.

FM1125 internal battery is used for detecting external voltage disconnection.

2.5 Electrical characteristics

| VALUE | Min. | Typ. | Max. | Unit |
|---|------|------|------|------|
| CHARACTERISTIC DESCRIPTION | | | | |
| Supply Voltage: | | | | |
| Supply Voltage (Recommended Operating Conditions) | 10 | | 30 | V |
| Digital Output (Open Drain grade): | | | | |
| Drain current (Digital Output OFF) | | | 120 | uA |
| Drain current (Digital Output ON, Recommended Operating Conditions) | | | 300 | mA |

| | | | | |
|--|-----|-------|----------------|------|
| Static Drain-Source resistance (Digital Output ON) | | | 300 | mOhm |
| Digital Input: | | | | |
| Input resistance (DIN1) | 15 | | | kOhm |
| Input Voltage (Recommended Operating Conditions) | 0 | | Supply voltage | V |
| Input Voltage threshold (DIN1) | | 7,5 | | V |
| Analog Input: | | | | |
| Input Voltage (Recommended Operating Conditions), Range1 | 0 | | 10 | V |
| Input resistance, Range1 | | 120 | | kOhm |
| Measurement error | | 1,43 | | % |
| Additional error | | ±12 | | mV |
| Input Voltage (Recommended Operating Conditions) Range2 | 0 | | 30 | V |
| Input resistance, Range2 | | 146,7 | | kOhm |
| Measurement error | | 1,75 | | % |
| Additional error | | ±36 | | mV |
| Output Supply Voltage 1-Wire:³ | | | | |
| Supply Voltage | 3,3 | | 3,6 | V |
| Output inner resistance | | 7 | | Ohm |
| Output current ($U_{out} > 3.0V$) | | 30 | | mA |
| Short circuit current ($U_{out} = 0$) | | 130 | | mA |



Note: Analog Input error margin can increase if temperature varies. If Analog input is not connected FM1125 will still measure certain numbers and it cannot be 0. This measurement is influenced by hardware components.

2.6 Absolute Maximum Ratings

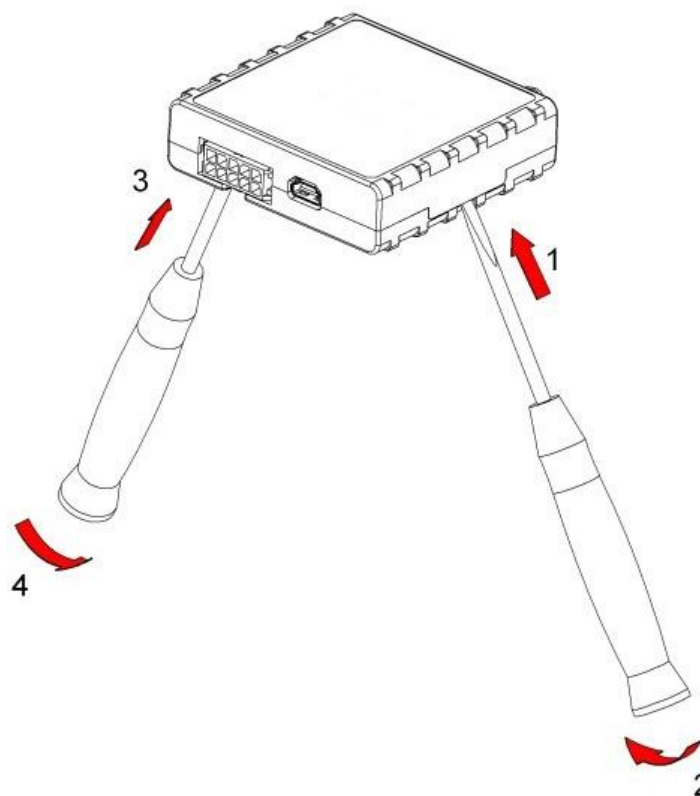
| CHARACTERISTIC DESCRIPTION | VALUE | Min. | Typ. | Max. | Unit |
|--|-------|------|------|------|------|
| Supply Voltage (Absolute Maximum Ratings) | | -32 | | 32 | V |
| Drain-Source clamp threshold voltage (Absolute Maximum Ratings), ($I_{drain} = 2mA$) | | | | 36 | V |
| Digital Input Voltage (Absolute Maximum Ratings) | | -32 | | 32 | V |

³ 1-wire Supply voltage PIN is dedicated for 1-wire devices ONLY, do not use it for any other purpose.

| | | | | |
|---|-----|--|----|---|
| Analog Input Voltage (Absolute Maximum Ratings) | -32 | | 32 | V |
|---|-----|--|----|---|

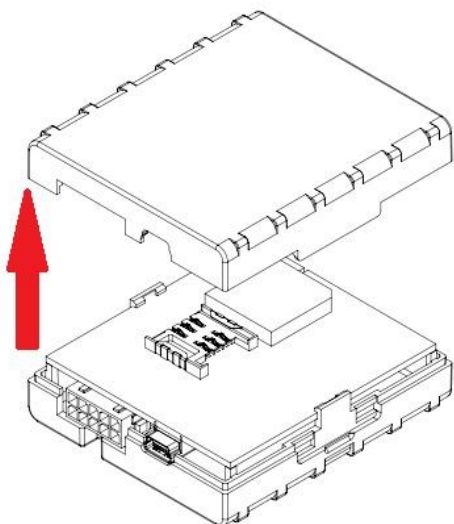
3 CONNECTION, PINOUT, ACCESSORIES

3.1 How to insert SIM card into FM1125 device:



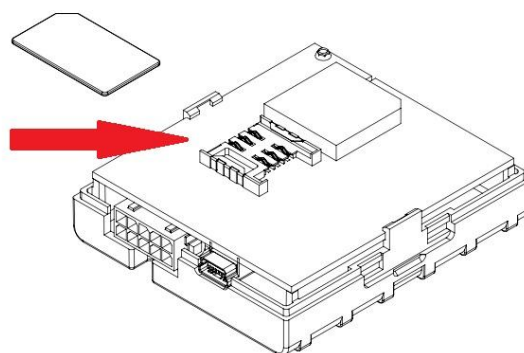
①

Gently open FM1125 case using screwdrivers



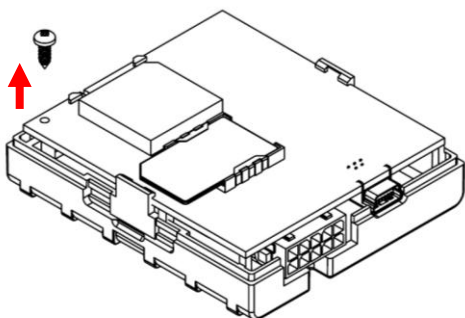
②

Remove FM1125 case



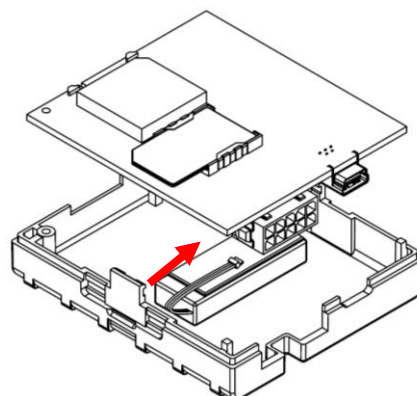
③

Insert SIM card as shown



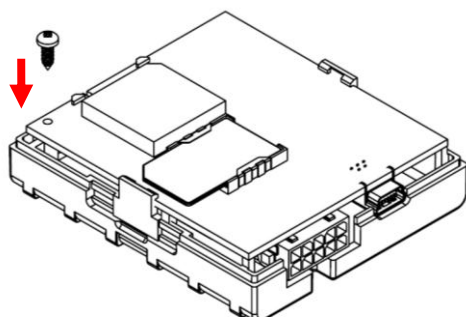
④

Unscrew antenna holding screw



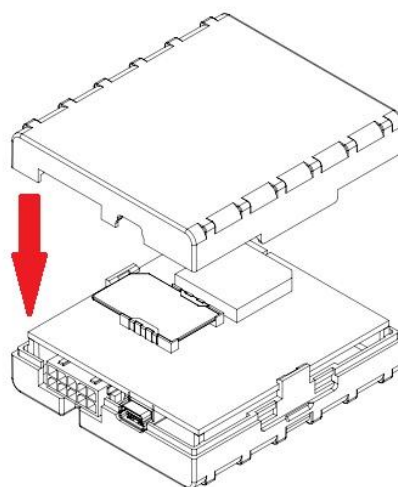
⑤

Insert battery wire to connector



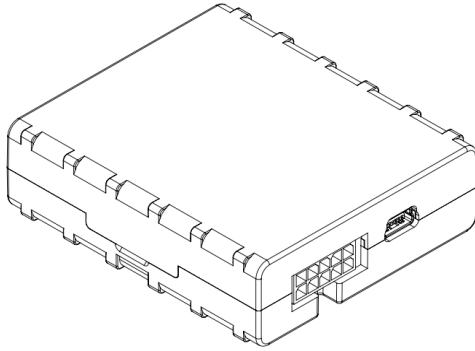
⑥

Screw in antenna holding screw



⑦

Attach top housing cover



⑧

Device is ready

3.2 Installing FM1125 drivers

Software requirements:

- Operating system 32-bit and 64-bit: Windows XP with SP3 or later, Windows Vista, Windows 7.
- MS .NET Framework V3.5 or later (<http://www.microsoft.com> or <http://avl1.teltonika.lt/downloads/tavl/Framework/dotnetfx35setupSP1.zip>).

Drivers:

Please download Virtual COM Port drivers from Teltonika website: http://avl1.teltonika.lt/downloads/FM11/vcpdriver_v1.3.1_setup.zip

Installing drivers:

Extract and run VCPDriver_V1.3.1_Setup.exe. This driver is used to detect FM1125 device connected to the computer. Click 'Next' in driver installation window (figures below):



Figure 2 Driver installation window

This will launch device driver installation wizard. In the following window click 'Next' button again:



Figure 3 Driver installation window

Setup will continue installing drivers and will display a window about successful process at the end. Click 'Finish' to complete setup:



Figure 4 Driver installation window

You have now installed drivers for FM1125 device successfully.

3.3 Navigate LED

| Behaviour | Meaning |
|-------------------------|--|
| Permanently switched on | GPS signal is not received |
| Blinking every second | Normal mode, GPS is working |
| Off | GPS is turned off because: <ul style="list-style-type: none"> • Deep sleep mode Or <ul style="list-style-type: none"> • GPS module is turned off |

3.4 Status LED

| Behaviour | Meaning |
|--------------------------------|--|
| Blinking every second | Normal mode |
| Blinking every 2 seconds | Deep sleep mode |
| Blinking fast for a short time | Modem activity |
| Blinking fast constantly | Boot mode |
| Off | <ul style="list-style-type: none"> • Device is not working Or <ul style="list-style-type: none"> • Device firmware being flashed |

3.5 Socket 2x5

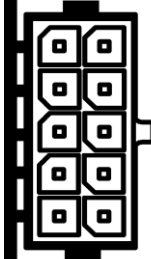
| | | | | |
|---------------------|---|---|----|---------------------------|
| DIN 1 (IGNITION) | 5 |  | 10 | RS485-B |
| AIN 1 | 4 | | 9 | RS485-A |
| OUT 1 | 3 | | 8 | RS232-RX |
| DATA_DALLAS | 2 | | 7 | RS232-TX |
| VCC (10÷30)V DC (+) | 1 | | 6 | GND (VCC (10÷30)V DC) (-) |

Figure 5 2x5 socket pinout

| Pin Nr. | Pin Name | Description |
|---------|------------------------|---|
| 1 | VCC (10÷30)V DC (+) | Power supply for module. Power supply range (10...30) V DC |
| 2 | DATA_DALLAS | Data channel for Dallas 1-Wire® devices |
| 3 | OUT 1 | Digital output. Channel 1. Open collector output. Max. --- 300mA. |
| 4 | AIN 1 | Analog input, channel 1. Input range: 0-30V/0-10V DC |
| 5 | DIN 1 | Digital input, channel 1 DEDICATED FOR IGNITION INPUT |
| 6 | GND(VCC(10÷30)V DC)(-) | Ground pin. (10÷30)V DC (—) |
| 7 | RS232-TX | Output for data transmit through RS232 |
| 8 | RS232-RX | Input for data receive through RS232 |
| 9 | RS485-A | Signal A wire for RS485 |
| 10 | RS485-B | Signal B wire for RS485 |

Table 2. Socket 2x5 pinout description

3.6 USB

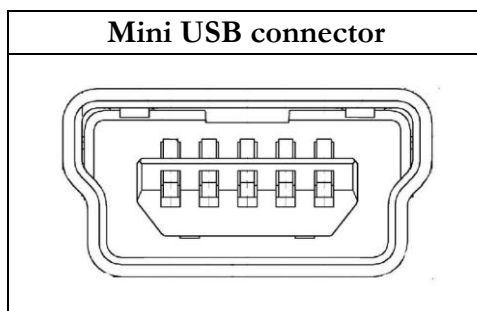


Figure 6 Mini USB type B connector

FM1125 connected to PC creates an STM Virtual COM Port, which can be used as a system port (to flash firmware and configure the device):

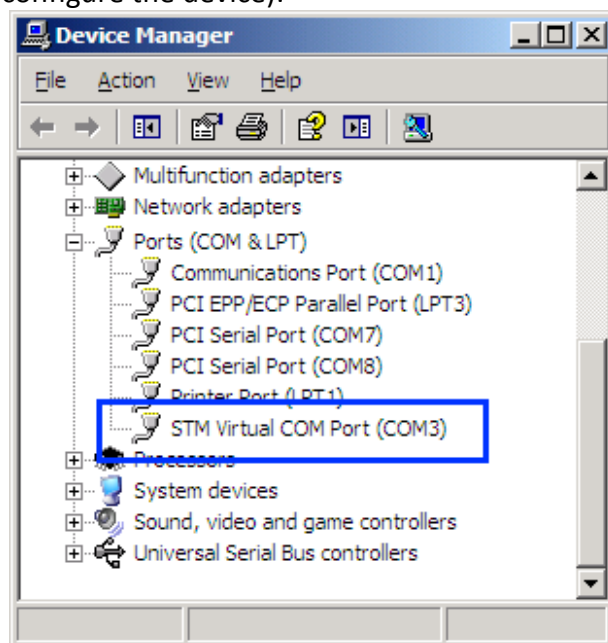


Figure 7 COM-Ports

3.7 Accessories



Note: Teltonika does not provide any additional equipment like panic buttons, door sensors or others.

1 – Wire devices

One of the realized features FM1125 is 1-Wire® data protocol, which enables connection of thermometer (DS1820, DS18S20 and DS18B20) and I-Button type: [DS1990A](#) (Figures 8 and 9 show FM1125 and 1-wire® device connection schemes).

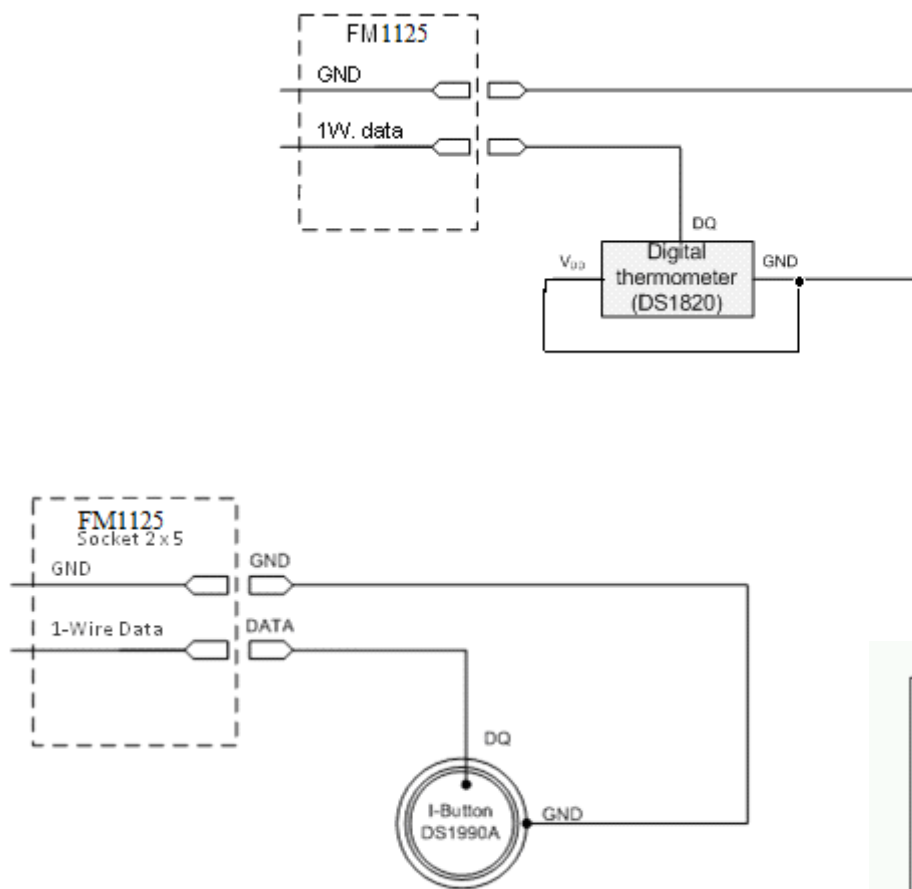


Figure 8 I-Button DS1990A connection scheme

Fuel Tank sensors

A fuel tank level sensor exists in most cars, which shows the approximate fuel level in the driver's indicator panel. It is possible to connect FM1125 Analog input to it (if sensor returns analogue signal proportional to fuel level). Figure 10 shows the connection scheme to the FM1125 and fuel tank sensor. After the connection to the tank fuel level sensor, calibration is needed. Calibration is needed

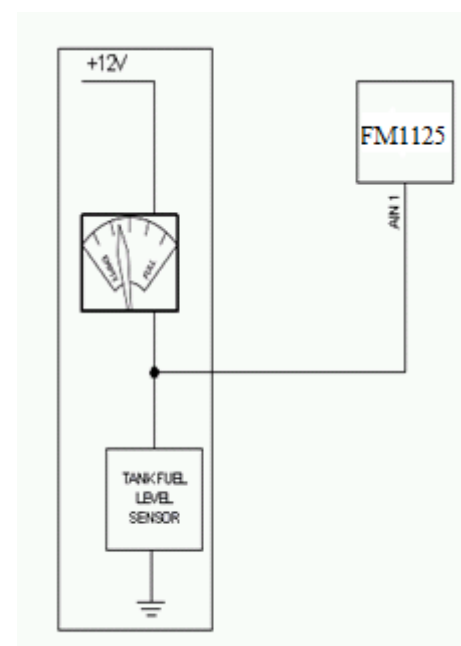


Figure 9 Fuel sensor scheme

because most fuel tank sensors are not linear. Calibration is performed by measuring voltage dependence on volume of fuel in tank.

Alarm buttons, door sensors, etc.

Alarm buttons, door sensors, ignition, etc. return two states: high or low voltage. Digital inputs are used to read this information. Figure below shows how to connect alarm button, door sensor, etc.

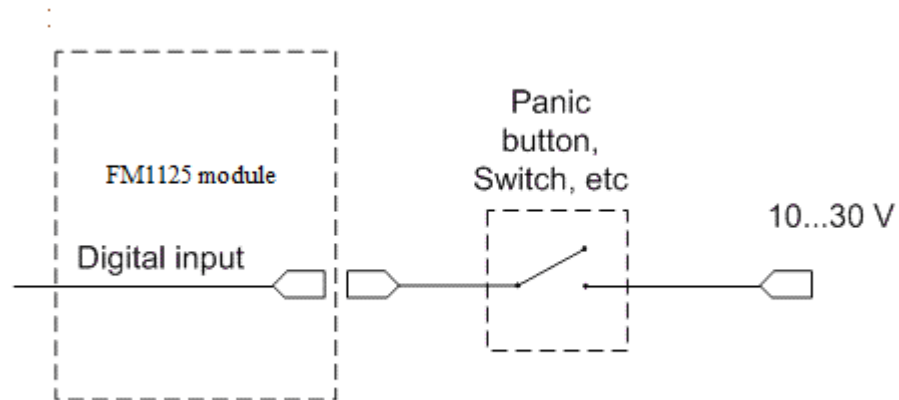


Figure 10 Panic button connection

In cases when sensor output signal is negative, an additional relay has to be installed to convert negative signal to positive.

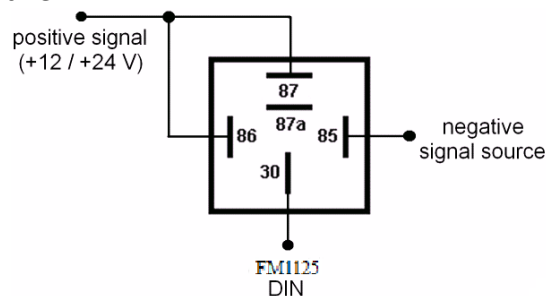


Figure 11 Inverting relay connection

Relays

An ordinary automotive relay is used to invert input signal or to immobilize engine starter. Note, that they are available as 12 V or 24 V.

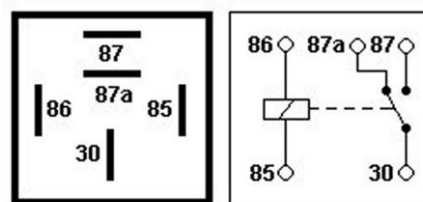


Figure 12 Automotive relay pinout

4 FIRMWARE

4.1 Updating firmware using USB cable

FM1125 functionality is always improving, new firmware versions are developed. Current module firmware version can be retrieved from Configurator. See configuration description for details.

Contact sales manager to get the latest firmware.

Connect FM1125 to PC with the USB cable. Launch “Firmware Updater”, select COM port to which device is connected, click connect, and when IMEI and Firmware version fields are filled, start the update. Device needs some time to send IMEI and Firmware version, so do not be afraid if IMEI will not show up immediately, disconnect and after 1-2 minutes try to connect again. Update process may take up to several minutes.

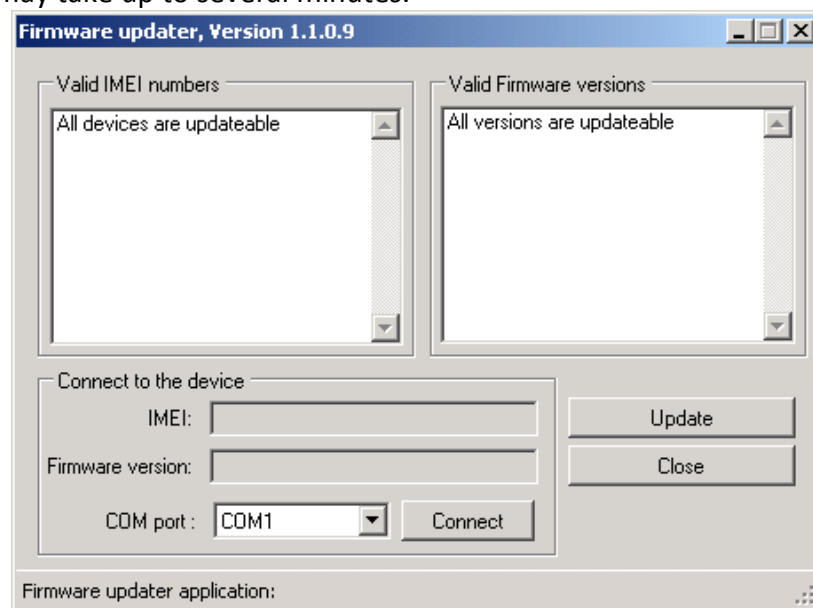


Figure 13 FM1125 firmware updater screen

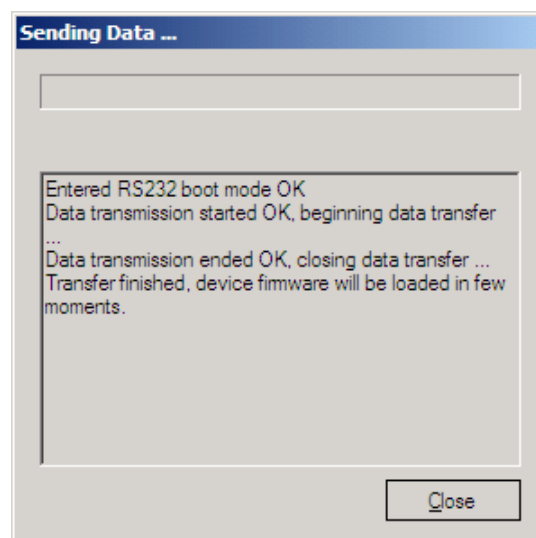


Figure 14 FM1125 firmware updating finished

When you see a table like in Figure 16, it means that the firmware is flashed to FM1125 successfully. You may now close the update window and start using your FM1125 device.

5 OPERATIONAL BASICS

5.1 *Operational principals*

FM1125 module is designed to acquire records and send them to the server. Records contain GPS data and I/O information. Module uses GPS receiver to acquire GPS data and is powered with three data acquire methods: time-based, distance-based and angle-based method. Note, that if FM1125 loses connection to GPS satellites, it continues to make records, however coordinate in these records remains the same (last known coordinate). Method's details are described in section 5.13. All data is stored in flash memory and later can be sent via GPRS or SMS. GPRS mode is the most preferred data sending mode. SMS mode is mostly used in areas without GPRS coverage or GPRS usage is too expensive.

GPRS and SMS settings are described in later sections. FM1125 communicates with server using special data protocol. Data protocol is described in device protocols documentation.

FM1125 can be managed by SMS commands. SMS Command list is described in SMS COMMAND LIST section. Module configuration can be performed over TCP or via SMS. Configuration parameters and modes are described in device protocols documentation. Please contact Teltonika sale manager to find out more about protocols documentation purchase.

5.2 *Sleep modes*

5.2.1 *Sleep mode*

FM1125 is able to go to sleep mode after configurable Sleep timeout. This timeout (defined period) starts counting when device is in STOP mode. After timeout is reached and all conditions for sleep mode are met, device goes to sleep mode. While in sleep mode, FM1125 turns GPS module off and it is not making new periodic records. Only event records is being recorded with last known coordinate and sent to AVL server. As a result power usage decreases allowing saving vehicle battery.

FM1125 can enter sleep mode if **ALL** of these conditions are met:

- FM1125 has to be configured to work in Sleep mode and Sleep timeout is reached;
- Device must be synchronized time with GPS satellites;
- No movement by movement sensor is detected;
- Ignition (DIN1) is off;
- USB cable detached;

FM1125 exits sleep mode when if **ONE** of following conditions are true:

- Movement by movement sensor is detected;
- Ignition (DIN1) is turned on;
- USB cable is connected;

5.2.2 *Deep Sleep mode*

While in deep sleep mode, FM1125 sets GPS receiver to sleep mode and turns off GSM/GPRS module (it is not possible to wake up device via SMS). Despite records with last

known coordinate are being saved and send to AVL server (GSM/GPRS module is turned on to send data and after that it is turned off again), power usage is decreased to save vehicle's battery. Note, that power saving depends on two configurable parameters: send period and min. record saving period.

FM1125 can enter deep sleep mode if **ALL** of these conditions are met:

- FM1125 has to be configured to work in Deep Sleep mode and Sleep timeout set;
- Device must be synchronized time with GPS satellites;
- No movement by movement sensor is detected;
- Ignition (DIN1) is off;
- USB cable detached;
- "Min. Record Saving Period" (Data Acquisition Mode settings) must be bigger value than "Sleep timeout" plus "Active Data Link Timeout" parameter.
- "Send period" (Data Acquisition Mode settings) must be bigger value than "Sleep timeout" plus "Active Data Link Timeout" parameter.

FM1125 exits deep sleep mode when if **ONE** of following conditions are true:

- Movement by movement sensor is detected;
- Ignition (DIN1) is turned on;
- USB cable is connected;



Note: In order to save GPRS traffic records saved in deep sleep mode do not contain below listed I/O elements information:
PDOP, HDOP, Odometer, Speedometer, iButton ID, Cell ID, Area Code, Temperature and GPS power

5.3 Virtual odometer

Virtual odometer is used to calculate traveled distance in FM1125 as a separate I/O element. When FM1125 detects movement, it starts counting distance using GPS signal: every second it checks current location and calculates distance between current and previous point. It keeps adding these intervals until it is time to make a record, then FM1125 records its location and adds odometer value, which is equal to the sum of all distances, measured every second. When record is made, odometer resets to zero and distance calculation starts all over again.

Virtual odometer as an I/O element can be also used with Trip feature, read chapters 5.4.2 and 5.14.2 for more details.

5.4 Features

Using available features can greatly increase FM1125 usability options.

5.4.1 Scenarios

Two scenarios are available on FM1125 device.

Digital Output No.1 is used by scenarios - Green Driving **or** Over Speeding;

Green Driving Scenario. Helps to prevent and inspect driver about harsh driving. Scenario continuously monitors: accelerating force, braking force and cornering angles. Warns driver if needed. DOUT1 is controlled by scenario for user needs, for example buzzer or LED.

To save GPRS traffic Green Driving **event** will be **generated (included into sent records) only** when FM1125 measured values are higher than those set in configuration, without additional I/O settings.

To prevent generating false events, harsh acceleration and harsh braking is monitored only when following conditions are fulfilled:

- Ignition is ON (DIN1 = 1)
- Vehicle speed is equal or higher than 10km/h

Harsh cornering is monitored only when following conditions are fulfilled:

- Ignition is ON (DIN1 = 1)
- Vehicle speed is equal or higher than 30km/h



Note: Green Driving Scenario is a factor on various cars and various drivers testing phase and can be subject to changes. Teltonika is constantly working on improvement of the functionality of the devices, and strongly recommends using the latest version of the firmware.

Over Speeding Scenario. Helps to prevent from exceeding fixed speed and inspects driver if needed. DOUT1 is controlled by scenario for user needs, to manage buzzer, LED, etc.

5.4.2 Trip

Trip customizable feature enables user extended monitoring of performed trips (from engine start at present location to engine stop at arrived location), log their start and stop points, view driven total distance⁴. Event will be **generated (included into send records) only** when trip starts and finishes.



Note: Scenarios and Trip features are activated (DOUTs are activated) only if DIN1=1 (ignition is on).

5.4.3 Geofencing

Geofencing is another feature which is highly customizable and can detect wherever car enters or leaves customized areas. More about Geofencing can be read in 5.14.3 chapter.

Auto Geofencing feature if enabled is activated automatically by turning off car ignition. Next time before driving user has to disable Auto Geofencing with iButton or by turning on car ignition. In case of theft car leaves Auto Geofencing zone without authorization FM1125 device automatically sends high priority record to AVL application.

⁴ Continuous odometer – total driven distance, works only in TRIP mode. Continues distance is counted only for ONE trip. If trip is finished (stop point is detected), odometer resets to 0 (zero). Next trip will start counting from the beginning.

5.4.4 iButton list

iButton list is used to enter authorized iButton ID codes, which are used to authenticate driver in Authorized driving and Auto Geofencing options.

5.5 CONFIGURATION

5.6 Configurator

New FM1125 module has default factory settings. Settings should be changed according to your application and your GSM operator information.

FM1125 configuration is performed via FM1125 Configurator program. FM1125 Configurator version can be downloaded from <http://avl1.teltonika.lt/downloads/FM11YX/>. Contact sales manager to get the latest FM1125 Configurator version. FM1125 configurator operates on Microsoft Windows OS and uses MS .Net Framework 3.5 or higher. Please ensure that MS .Net Framework 3.5 or later is installed on your PC before starting configurator. Latest MS .Net Framework version can be downloaded from official Microsoft web page.

Module configuration is performed over USB cable. Configuration process starts from starting FM1125 Configurator program and then connecting to FM1125 device via Connect button located on the top left corner of configurator. If connected successfully IMEI, Version fields which were empty, now are filled with certain numbers depending on Modem IMEI and firmware version of your device (figure below).

FM1125 has one user editable profile, which can be loaded from device, and saved. User can also revert to default settings, by pressing Load Defaults button. After any modification of configuration settings it has to be saved to FM1125 device, otherwise it will not be written to device.

FM1125 has 2 configuration modes: Recommended Configuration (Figure 17) and Advanced Configuration (Figure 18).

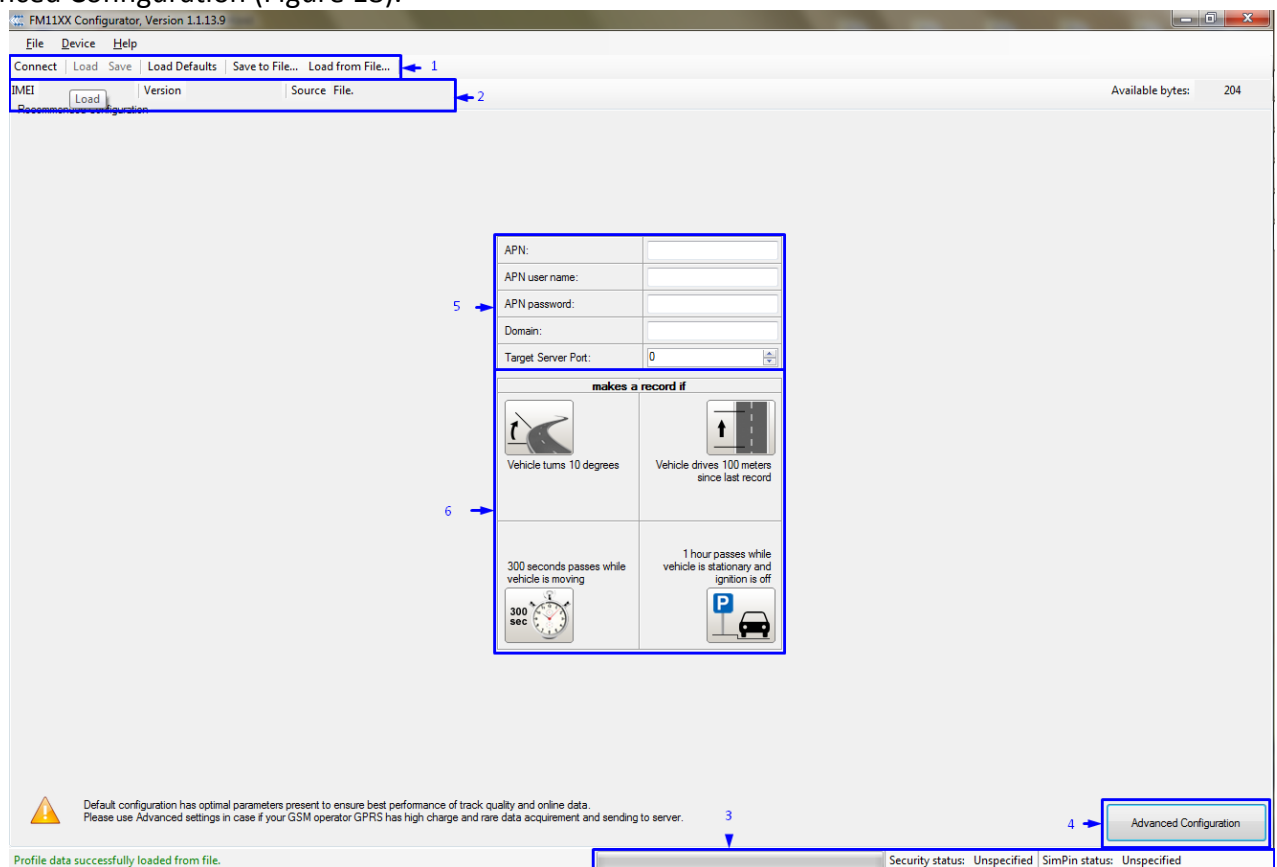


Figure 15 Recommended Configuration window

Recommended Configuration mode uses predefined data acquisition values. In this configuration mode it is only required to enter network parameters. In Advanced Configuration mode FM1125 is more configurable.

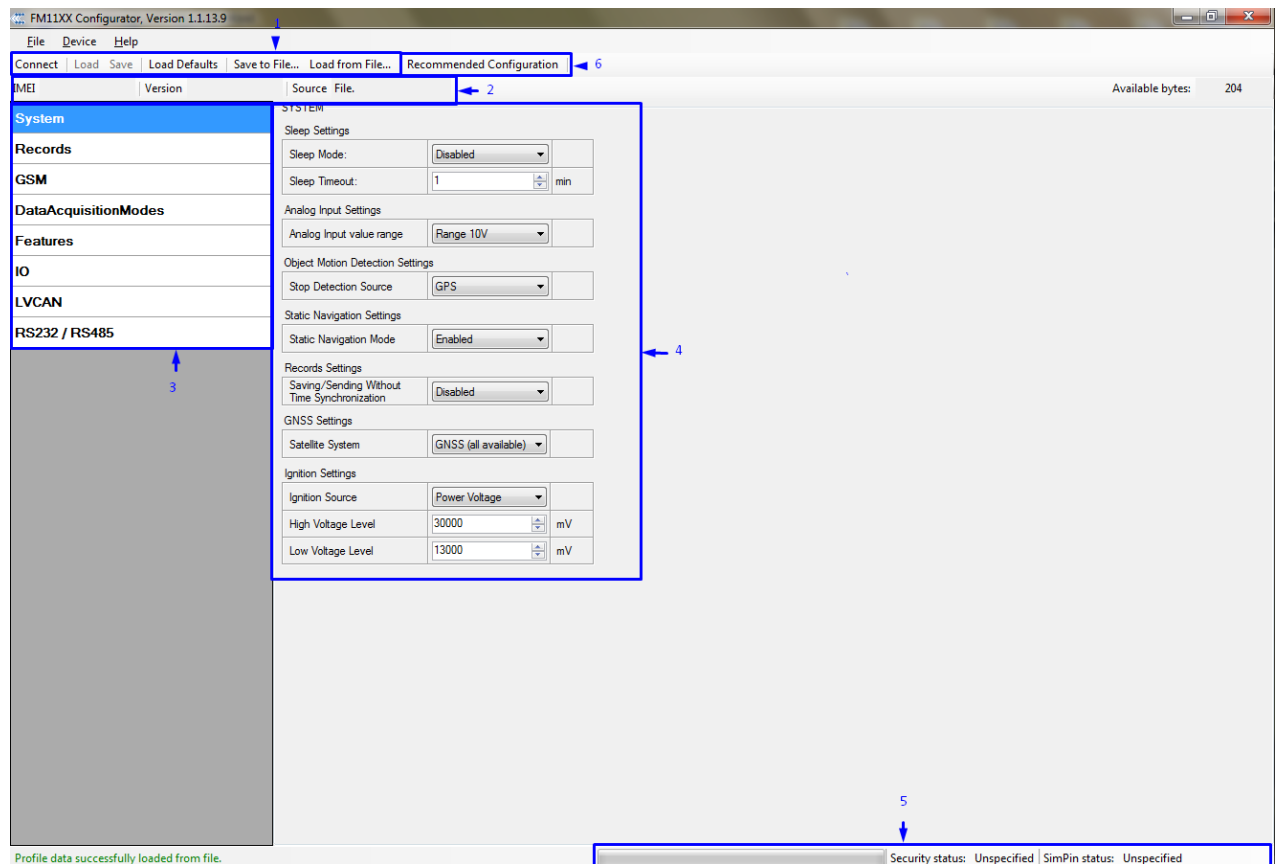


Figure 16 Advanced Configuration window

FM1125 Configurator is divided into main areas: 1 – main button area, 2 – information area, 3 – settings menu, 4 – parameters and values menu, 5 – information about connection. Button 6 is used to change between configuration modes.

Main Buttons description:

- 'Connect' – connects device
- 'Load' – reads configuration parameters from FM1125 Flash memory.
- 'Save' – saves configuration parameters to FM1125 Flash memory.
- 'Load Defaults' – loads default FM1125 settings that later can be modified. This procedure must be performed before entering new parameters.
- 'Save to File...' – allows user to save currently entered settings to .XML file, for later usage.
- 'Load from File...' – allows user to load configuration saved in .XML extension file.
- 'Reset device' – reboots FM1125 and displays processor firmware version.

Additional Buttons description:

'SIM PIN' - allows to enter PIN code if inserted SIM card has activated PIN code security. Note that PIN code can be entered 2 times.

'Add Keyword' / 'Change Keyword' / 'Switch Security Off' – buttons are used to protect configurator from unauthorized access to configuration.

Keyword is 4 – 10 symbol length. If keyword is set, every time user reconnects FM1125 to USB port, user will be asked to provide valid keyword when connecting FM1125 to configurator. User is given 5 attempts to enter keyword. After entering valid keyword, counter resets to 5.

If user disconnects FM1125 using 'Disconnect' button and does not disconnect from USB port, after reconnecting using 'Connect' button, configurator does not ask for keyword.



ATTENTION! If you have entered a keyword, disconnected from the configurator and then later connected again, you will need to enter the keyword that you have entered previously. If you have forgotten it, please contact your local sales manager.

5.7 Record storage

FM1125 can store up to 8000 data records if GSM or GPRS is not available at the moment. It will send data later when GPRS is available again. Note that FM1125 can have memory full of records. In such case it will start deleting oldest records in order to save new ones. Sending all the data records to server may take some time. Sending 8000 records for FM1125 may take for about 2 hours (exact time may differ depending on GPRS/server load).

You can access all uploaded data from TAVL4 application.

More details on how to use TAVL application please refer to "TAVL4 application user manual" documentation.

5.8 System settings

System settings have 4 configurable parameters:

- Deep sleep settings, where user can turn deep sleep on or off
- Analog Input Settings, where user can choose analog input range 10 V or 30 V, depending on needed accuracy (lower range gives higher accuracy of measurements), and input voltage
- Object Motion Detection Settings, where user can configure 3 ways how FM1125 will detect stopped movement, and change its working mode (for working modes, read section 5.13)
- Static navigation settings, where user can turn static navigation on or off
- Static navigation settings, where user can turn static navigation on or off
- Records Settings, where user can enable or disable records when GPS is not available (no time synchronization)
- GNSS Settings, where user can choose satellite system

| Stop Detection Source | Vehicle on Stop mode | Vehicle Moving mode |
|---------------------------|---|--|
| Ignition (recommended) | If ignition (DIN1) is logic low | If ignition (DIN1) is logic high |
| Msensor (movement sensor) | Internal movement sensor does not detect movement | Internal movement sensor detects movement |
| GPS | GPS fix is available and vehicle speed is lower than 5 km/h | GPS fix is available and vehicle speed is higher than 5 km/h |
| | While GPS fix is unavailable, Object Motion Detection Settings are working like in Msensor mode | |

Static Navigation Mode is a filter, which filters out track jumps when the object is stationary. If Static navigation filter is disabled, it will apply no changes on GPS data. If Static navigation filter is enabled, it will filter changes in GPS position if no movement is detected (depends on Object Motion Detection Settings). It allows filtering GPS jumps when object is parked (is not moving) and GPS position is still traced.

| System | SYSTEM |
|----------------------|--|
| Records | Sleep Settings Sleep Mode: <input type="text" value="Disabled"/> Sleep Timeout: <input type="text" value="1"/> min |
| GSM | Analog Input Settings Analog Input value range: <input type="text" value="Range 10V"/> |
| DataAcquisitionModes | Object Motion Detection Settings Stop Detection Source: <input type="text" value="GPS"/> |
| Features | Static Navigation Settings Static Navigation Mode: <input type="text" value="Enabled"/> |
| IO | Records Settings Saving/Sending Without Time Synchronization: <input type="text" value="Disabled"/> |
| LVCAN | GNSS Settings Satellite System: <input type="text" value="GNSS (all available)"/> |
| RS232 / RS485 | Ignition Settings Ignition Source: <input type="text" value="Power Voltage"/> High Voltage Level: <input type="text" value="30000"/> mV Low Voltage Level: <input type="text" value="13000"/> mV |

Figure 17 System settings configuration

5.9 Records settings

Here user can modify if FM1125 device will send newest records first, meaning, that the most important thing is to know recent position of car, older records are being sent right after newest records arrive to AVL application.

Activate Data Link Timeout is used to set timeout of link between FM1125 and AVL application termination. If FM1125 has already sent all records it waits for new records before closing link. If new records are generated in the period of this timeout, and minimum count to send is reached, they are sent to AVL application. This option is useful when GSM operator charge for link activation.

Server Response Timeout is used to set time period waiting for response from server side.

| System | RECORDS |
|----------------------|--|
| Records | Record Settings Sorting: <input type="text" value="From newest"/> Active Data Link Timeout: <input type="text" value="5"/> sec. Server Response Timeout: <input type="text" value="300"/> sec. |
| GSM | |
| DataAcquisitionModes | |

Figure 18 Records settings configuration

5.10 GSM settings, GPRS part

'GPRS' defines main parameters for FM1125: GSM operator APN and GPRS username and password (optional – depending on operator), destination server IP and port, and allows to set protocol used for data transfers – TCP or UDP

Some operators use specific authentication for GPRS session – CHAP or PAP. If any of these is used, APN should be entered as ‘chap:<APN>’ or ‘pap:<APN>’. I.e. if operator is using APN ‘internet’ with CHAP authentication, it should be entered as ‘chap:internet’. Information about APN and authentication type should be provided by your GSM operator.

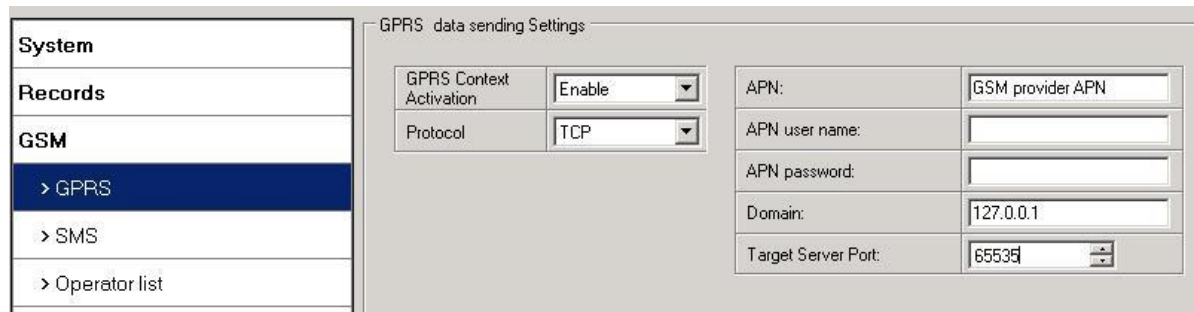


Figure 19 GPRS configuration

5.11 GSM settings, SMS part

Essential fields in ‘SMS’ part are ‘Login’ and ‘Password’. The login and password are used with every SMS sent to FM1125. If login and password are not set, in every SMS sent to FM1125 device two spaces before command have to be used (<space><space><command>).

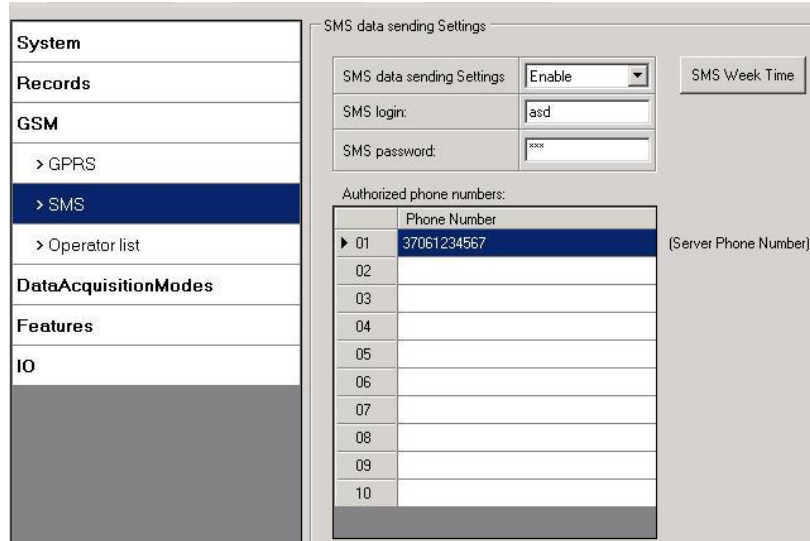
Command structure with set login and password:

<login><space><password><space><command>, example: “asd 123 getgps”

Phone numbers have to be written in international standard, without using “+” or “00” signs in prefix. If no numbers are entered, configuration and sending commands over SMS are allowed from all GSM numbers.

SMS data sending settings – enable or disable **periodic** data and event SMS usage. This setting does not affect replies to SMS request messages – answers are always sent back to sender telephone number.

FM1125 can send binary SMS with 24-coordinates-in-one-SMS. It is used in areas where no GPRS coverage is available. Module collects data and sends to server binary SMS containing information about last 24 collected points. SMS sending schedule is set in SMS Week Time tab. 24-Coordinates SMS decoding is described in device protocols documentation. Please contact Teltonika sale manager to find out more about protocols documentation purchase.



| | Phone Number |
|----|--------------|
| 01 | 37061234567 |
| 02 | |
| 03 | |
| 04 | |
| 05 | |
| 06 | |
| 07 | |
| 08 | |
| 09 | |
| 10 | |

Figure 20 SMS configuration



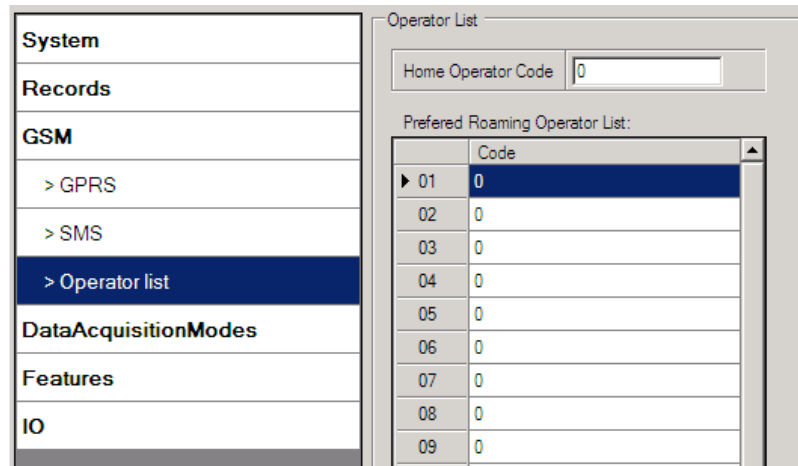
Note: A mobile phone will not understand and SMS with binary code, so sending it to a mobile phone is useless. When sending a binary SMS to a phone number, which is a server phone number, the server can interpret and understand binary code, so the data can be read and you can view it on the server.



SMS login and password and authorized number list are used to protect FM1125 module from unauthorized access. Module accepts messages only from a list of authorized numbers and with proper module login and password. Numbers must be without “+” or “00” prefix. If no authorized numbers are entered, module accepts messages from all numbers.

5.12 GSM settings, Operator list

Operators list – FM1125 can work in different modes (use different settings) according to the operator list defined. Operator list is used for Data Acquisition Mode switching (see chapter 5.13 Data Acquisition Mode settings for more details). Modes are changed based on GSM operator FM1125 is connected to.



| | Code |
|----|------|
| 01 | 0 |
| 02 | 0 |
| 03 | 0 |
| 04 | 0 |
| 05 | 0 |
| 06 | 0 |
| 07 | 0 |
| 08 | 0 |
| 09 | 0 |

Figure 21 Operator list configuration

If operator list is left empty, it will allow using GPRS to any GSM operator. Please note that FM1125 will work in **Unknown mode only** (make sure it is configured to allow data sending – GPRS context is enabled).

5.13 Data Acquisition Mode settings

Data Acquisition Modes are an essential part of FM1125 device, it is also highly configurable.

By configuration user defines how records will be saved and sent. There are three different modes: Home, Roaming and Unknown. All these modes with configured data acquisition and send frequencies depend on current GSM Operator defined in Operator list (see section 5.12) and are switched when GSM operator changes (e.g. vehicle passes through country boarder).

If current GSM operator is defined as Home Operator, device will work in Home Data Acquisition mode, if current operator is defined as Roaming Operator, device will work in Roaming Data Acquisition mode, and if current operator code is not written in Operator list (but there is at least one operator code in the operator list), device will work in Unknown Acquisition mode.

This functionality allows having different AVL records acquire and send parameters values when object is moving or stands still. Vehicle moving or stop state is defined by Stop Detection Source parameter. There are 3 ways for FM1125 to switch between Vehicle on Stop and Vehicle Moving modes see section 5.7.

FM1125 allows having 6 different modes. Operational logic is shown in Figure 24.



If there are no operator codes entered into operator list, FM1125 will work in Unknown network mode ONLY.

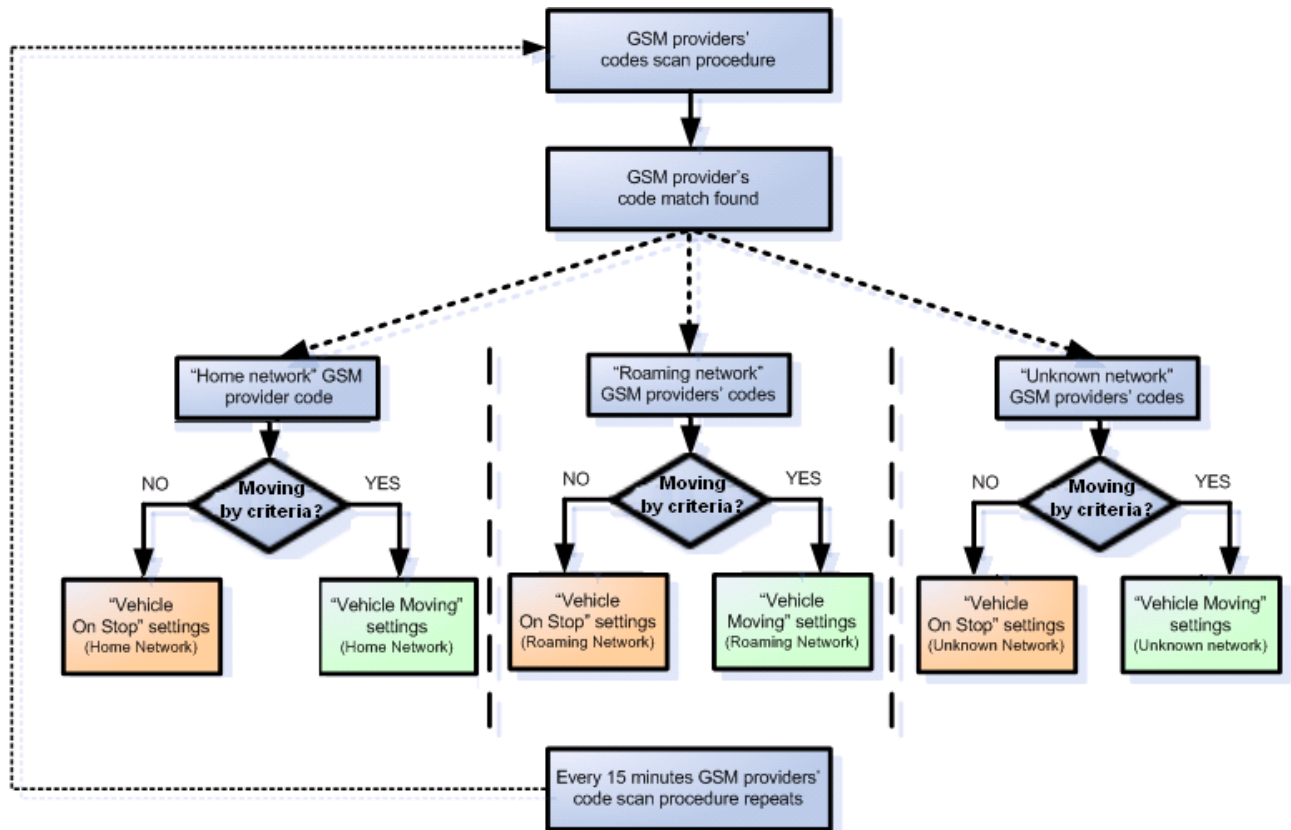


Figure 22 Data Acquisition Mode configuration

Operator search is performed every 15 minutes. Depending on current GSM operator, Home, Roaming or Unknown mode can be changed faster than every 15 minutes. This process is separate from operator search. Movement criteria are checked every second.

| System | Data Acquisition Modes : Home | | | |
|----------------------|-------------------------------|----------|--------------------|----------|
| Records | | | | |
| GSM | | | | |
| DataAcquisitionModes | | | | |
| | Vehicle on STOP | | Vehicle MOVING | |
| > Home | Min Period: | 600 sec. | Min Period: | 600 sec. |
| > Roaming | | | Min Distance: | 1000 m. |
| > Unknow | | | Min Angle: | 30 deg. |
| Features | Min Saved Records: | 10 | Min Saved Records: | 10 |
| | Send Period: | 600 sec. | Send Period: | 600 sec. |
| | GPRS Week Time | | GPRS Week Time | |

| System | Data Acquisition Modes : Roaming | | | |
|----------------------|----------------------------------|----------|--------------------|----------|
| Records | | | | |
| GSM | | | | |
| DataAcquisitionModes | | | | |
| > Home | Vehicle on STOP | | Vehicle MOVING | |
| > Roaming | Min Period: | 600 sec. | Min Period: | 600 sec. |
| > Unknow | | | Min Distance: | 1000 m. |
| Features | | | Min Angle: | 30 deg. |
| | Min Saved Records: | 10 | Min Saved Records: | 10 |
| | Send Period: | 600 sec. | Send Period: | 600 sec. |
| | GPRS Week Time | | GPRS Week Time | |

Figure 23 Data Acquisition Mode configuration

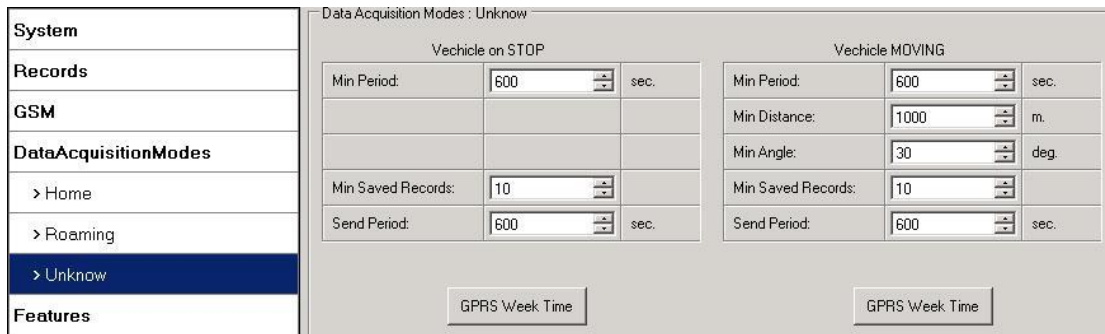


Figure 24 Data Acquisition Mode configuration

'Min Saved Records' defines minimum number of coordinates and I/O data that should be transferred with one connection to server. If FM1125 does not have enough coordinates to send to server, it will check again after time interval defined in 'Sending Period'

Send period – GPRS data sending to server period. Module makes attempts to send collected data to server every defined period. If it does not have enough records (depends on parameter Min. Saved Records described above), it tries again after defined time interval.

GPRS Week Time tab – most GSM billing systems charge number of bytes (kilobytes) transmitted per session. During the session, FM1125 makes connection and transmits data to a server. FM1125 tries to handle the session as much as possible; it never closes session by itself. Session can last for hours, days, weeks or session can be closed after every connection in certain GSM networks – this depends on GSM network provider. GPRS Context Week Time defines session re-establish schedule if session was closed by network. New GPRS context is opened if time is 10 minutes till time checked in table. Therefore if all boxes are checked, FM1125 is able to open new connection anytime. At scheduled time match FM1125 checks for GPRS session activity. If GPRS session is alive, FM1125 sends data to server according to Send period parameter. If it is not, FM1125 checks if it is able to re-establish the session.

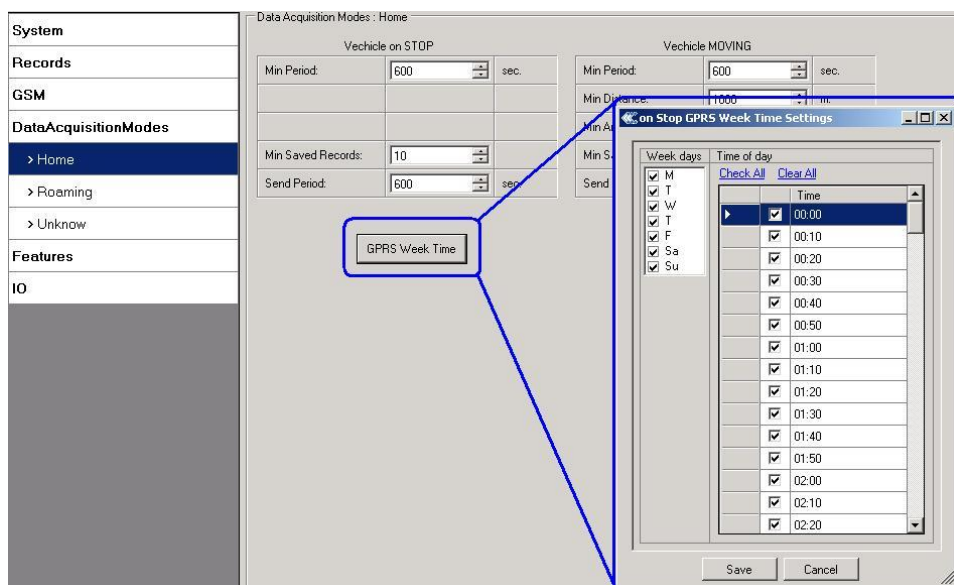


Figure 25 GPRS Week Time configuration

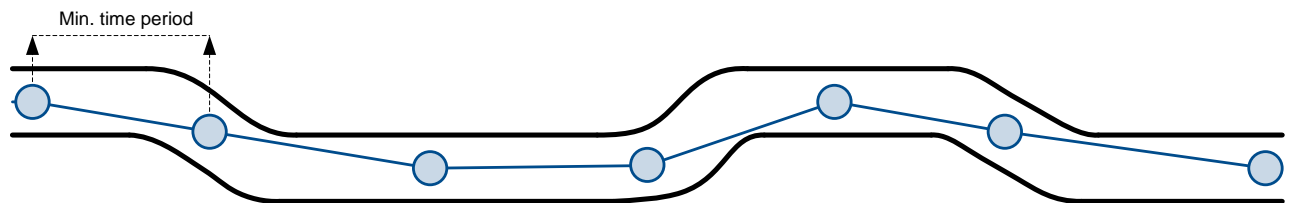
Device checks if the time between last saved record and current time is equal or higher than Time based acquire interval. If so, FM1125 saves record to memory. If not, FM1125 checks if the distance from last record to current record is equal or higher than Distance based acquire interval. If so, saves the record to memory. If not and speed is higher than 10km/h, then FM1125 checks if angle difference between last record and current record is equal or higher than Angle based acquire value. If so, saves the record to memory. These checks are performed every second.



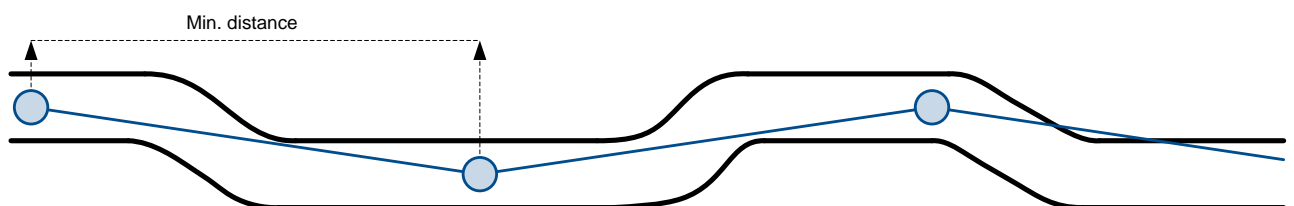
Note: Keep in mind that FM1125 operates in **GMT:0** time zone, without daylight saving.

FM1125 is able to collect records using three methods at the same time: time, distance and angle based data acquisition:

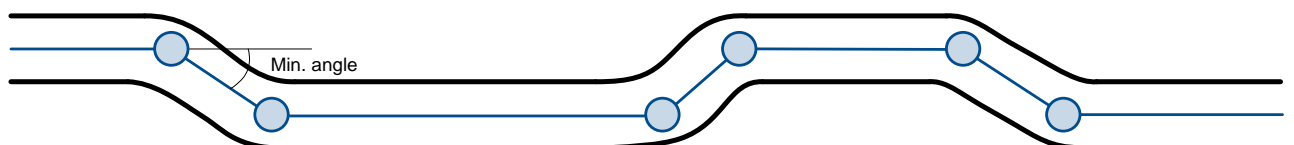
Time based data acquiring (Min. period) – records are being acquired every time when defined interval of time passes. Entering zero disables data acquisition depending on time.



Distance based data acquiring (Min. distance) – records are being acquired when the distance between previous coordinate and current position is greater than defined parameter value. Entering zero disables data acquisition depending on distance.



Angle based data acquiring (Min. angle) – records are being acquired when angle difference between last recorded coordinate and current position is greater than defined value. Entering zero disables data acquisition depending on angle.



5.14 Features settings

For more information about available Scenarios, Trip, Geofencing and iButton list, refer to 5.4 chapter.

5.14.1 Scenarios settings

In Scenarios window two different scenarios are available. Only one per digital output can be active at a same time, e.g. DOUT1 can have either Green driving **or** Over Speeding enabled.

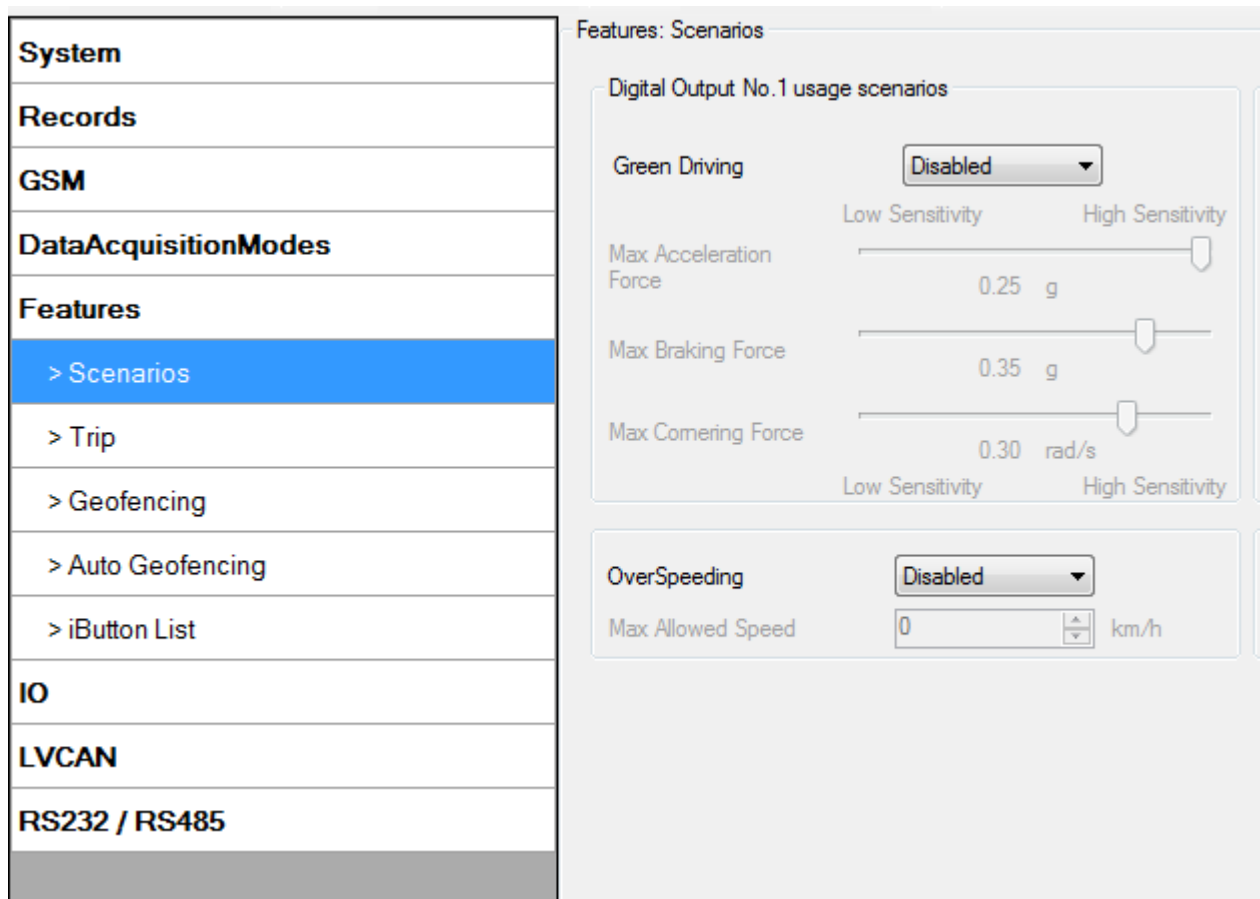


Figure 26 Scenarios configuration

Digital Output (open drain grade) usage in scenarios:

- Green Driving
DOUT1 is ON for:
 - 3sec. if detected value is over (0; 30] % from preconfigured allowed value
 - 5sec. if detected value is over (30; 50] % from preconfigured allowed value
 - 7sec. if detected value is over (50; -] % from preconfigured allowed value
 After period of time DOUT1 is turned OFF.
- Over Speeding
DOUT1 is ON, while vehicle speed exceeds parameter value. DOUT1 is activated until current speed decreases below parameter value.

5.14.2 Trip settings

Trip window offers user to configure Trip feature. If Trip is enabled configuration of parameters are enabled.

Start Speed – GPS speed has to be greater than the specified Start Speed in order to detect Trip Start.

Ignition Off Timeout – timeout to wait if ignition was off, to detect Trip stop.

Continuous distance counting – Not or Continuous can be chosen. For this feature I/O Odometer must be enabled.

If I/O Odometer is enabled and Continuous distance counting variable is set to Continuous, **Trip distance** is going to be counted continuously (**from Trip start to Trip stop**). This value is written to I/O Odometer value field. When Trip is over and next Trip begins, Odometer value is reset to zero. When the next trip starts counting continuously starts from the beginning again.

If I/O Odometer is enabled and Continuous Distance Counting variable is set “Not”, then the distance is going to be counted only between every record made. This value is written to I/O Odometer value field and reset to zero every new record until Trip stops. If later all Odometer values are summed up manually, the user gets the distance driven during the whole period of the Trip.

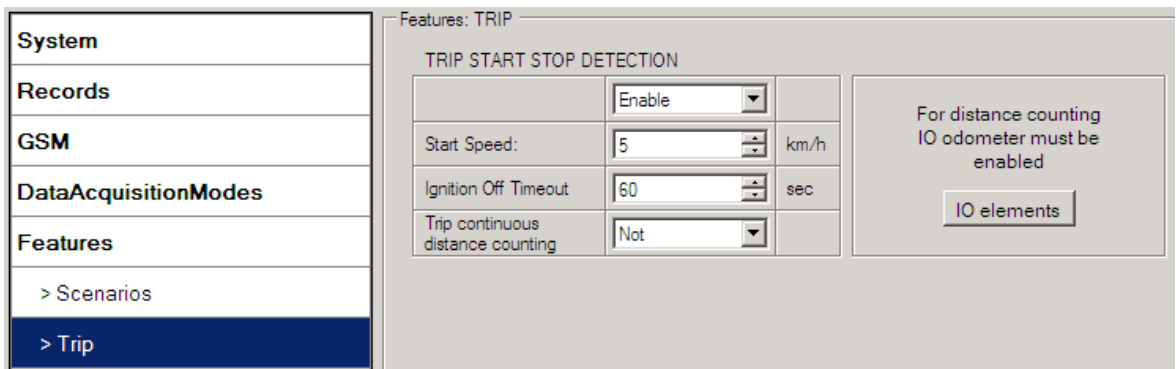


Figure 27 Trip configuration

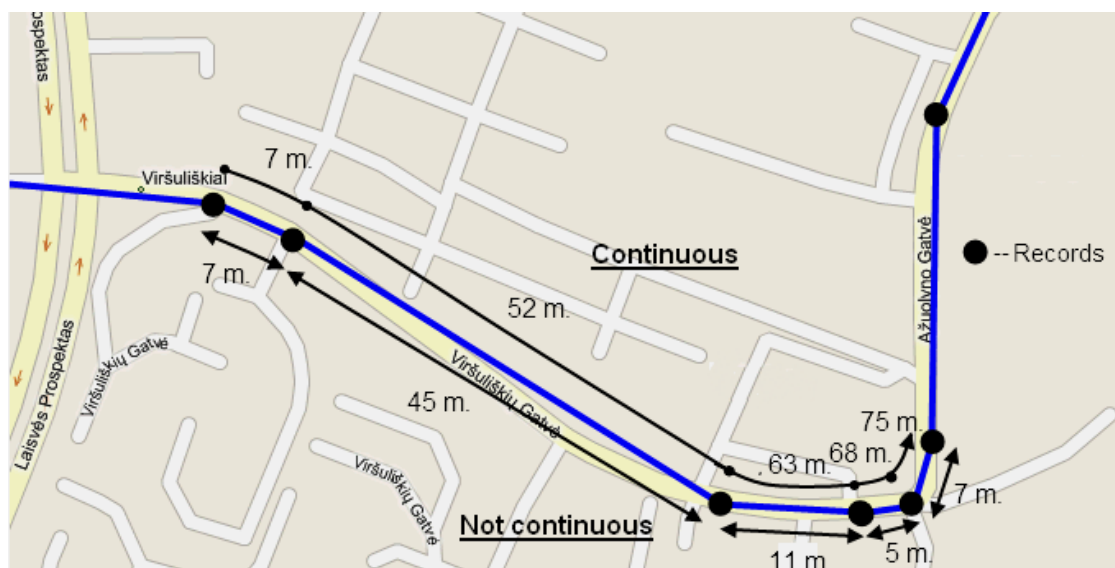


Figure 28 Trip continuous distance counting parameter example

5.14.3 Geofencing settings

FM1125 has 5 configurable Geofence zones and it can generate an event when defined Geofence zone border is crossed.

Frame border – frame border is an additional border around Geofence zone. It is additional area around defined zone used to prevent false event recording when object stops on the border of the area and because of GPS errors some records are made inside area and some – outside. Event is generated only when both borders are crossed. See figure 31 for details: track 1 is considered to have entered the area while track 2 is not.

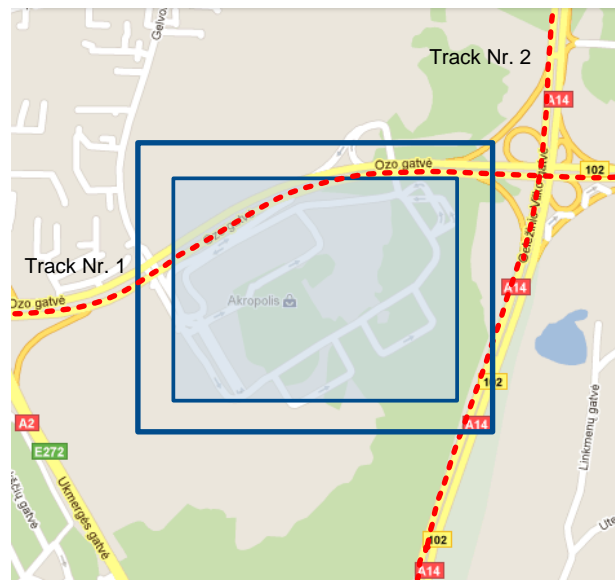


Figure 29 Geofence border

Shape – can be rectangle or circle

Priority – priority of Geofence event: low, high or panic. These levels define priority of event information sending to server. See I/O element description for more details about priorities.

Generate event (On entrance, On exit, On Both) – choose when record will be generated;

X1 – geofence zone left bottom corner X coordinate (longitude);

Y1 – geofence zone left bottom corner Y coordinate (latitude);

X2 or R – geofence zone upper right corner X coordinate (longitude) or radius of circle when Circular zone is used (radius in meters);

Y2 – geofence zone upper right corner Y coordinate (latitude);

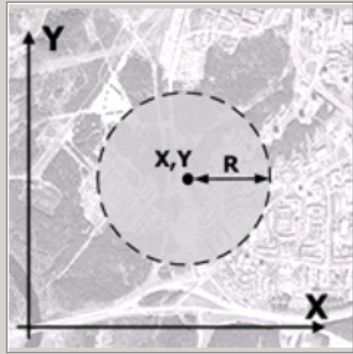
| | | |
|-----------------------------|-------------------------|---|
| System | FEATURES: Geofencing | |
| Records | Geofencing | |
| GSM | Frame border: 1000 m. |  |
| DataAcquisitionModes | Geofence zone: Zone 1 | |
| Features | Shape: Circle | |
| > Scenarios | Priority: High | |
| > Trip | Generate Event: On Both | |
| > Geofencing | Longitude (X): 0.000000 | |
| > iButton List | Latitude (Y): 0.000000 | Radius: 0 m. |

Figure 30 Geofence configuration

AutoGeofencing settings

AutoGeofence – the last known position after movement = off. If your car's being taken away – you can be notified. The shape and size of the geofence zones are parameters. It is possibility to state whether entering in or out of the geofence triggers an asynchronous message.

AutoGeofencing option can be configured by following parameters visible in figure 33 below.

Activate – Enable or Disable AutoGeofence functionality.

Activation TMO – Time period before Geofence is activated after vehicle stops.

Deactivate By:

Ignition – If ignition becomes high it will disable AutoGeofence Zone.

iButton – if iButton is attached it will disable AutoGeofence Zone.

Edit iButton List – if list is not empty, attached iButton is tested against an iButton list, if match is found AutoGeofence zone is disabled.

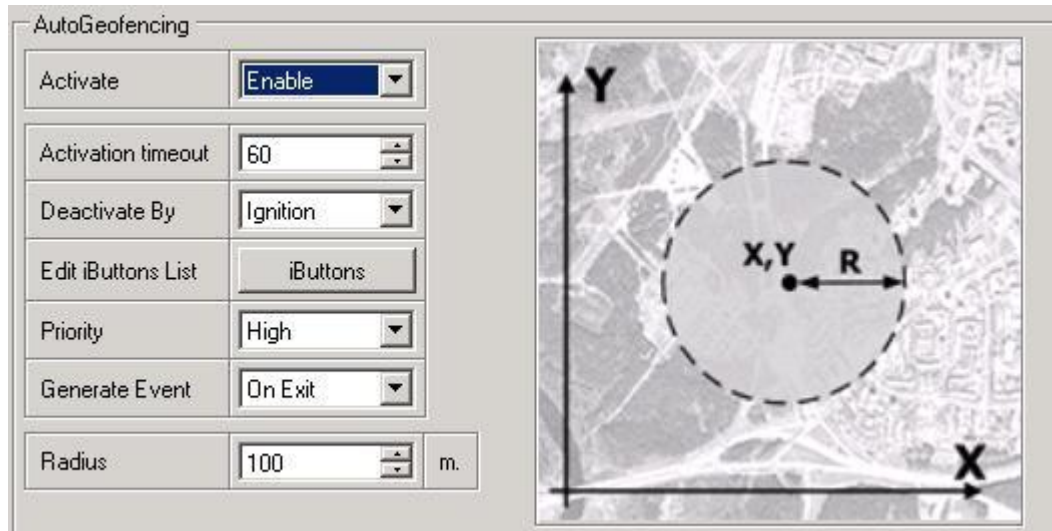
Priority – Priority of generated event, which will be applied to saved record.

Enter Event – Event generation on Geofence entrance.

Exit Event – Event generation on Geofence exit.

On Both - Event generation on Geofence entrance Or exit

Note that AutoGeofencing does not require entering coordinates, instead it requires GPS visibility. If vehicle stopped and activation timeout has passed, an AutoGeofence will be created around vehicle's last position with set Radius value. AutoGeofence event generation works the same as Geofencing mentioned above.



The image shows a software window titled "AutoGeofencing". It contains several configuration options:

- Activate:** A dropdown menu set to "Enable".
- Activation timeout:** A numeric input field set to "60".
- Deactivate By:** A dropdown menu set to "Ignition".
- Edit iButtons List:** A button labeled "iButtons".
- Priority:** A dropdown menu set to "High".
- Generate Event:** A dropdown menu set to "On Exit".
- Radius:** A numeric input field set to "100" with a unit "m." (meters) next to it.

To the right of these settings is a map view showing a circular geofence. The center of the circle is marked with a dot and labeled "X,Y". A horizontal line from the center to the edge of the circle is labeled "R", representing the radius. The map has a coordinate system with "Y" and "X" axes.

Figure 31 Geofence configuration



Note: FM1125 operates GMT:0 time without daylight saving.

5.14.4 SMS events

SMS events functionality allows FM1125 to send a configured SMS when an event is triggered. This event can be triggered by:

- Green Driving
- OverSpeeding
- Trip start/stop
- Geofence
- AutoGeofence
- I/O event

When any of the above events is triggered, FM1125 sends a configured SMS message to a defined phone number. If SMS events is activated, but there are no numbers defined in SMS events PreDefined Numbers list (figure 34), then the device will not send any messages.

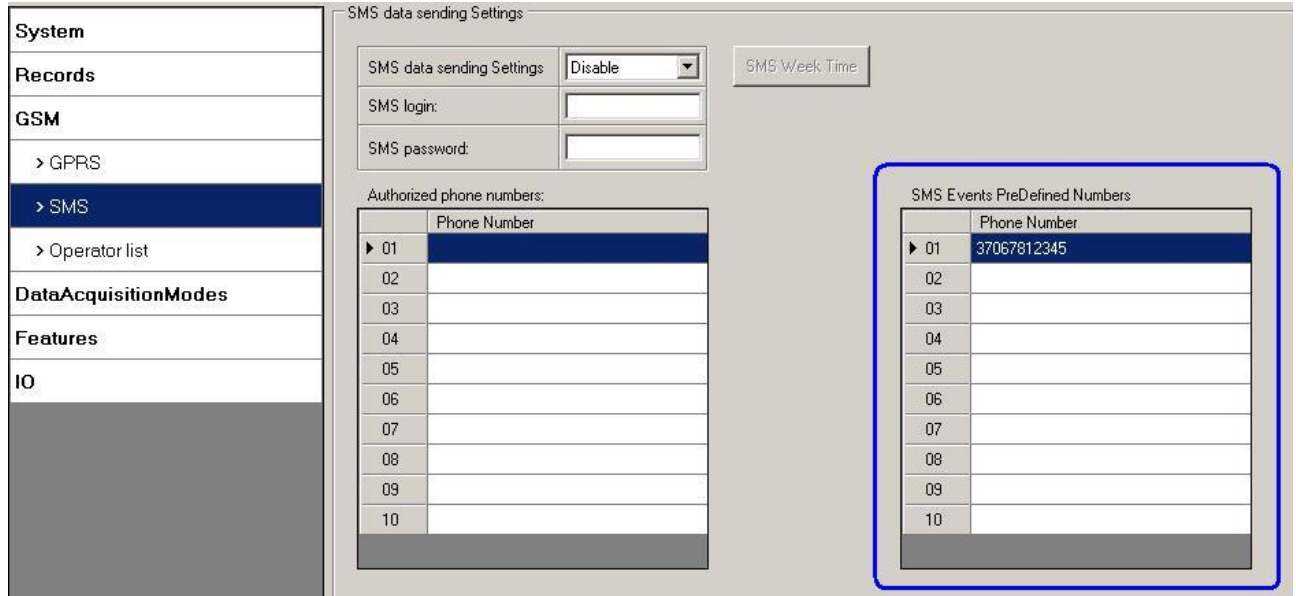


Figure 32 SMS Events PreDefined Numbers list

The sent SMS messages format is according to:

"Date Time EventText"

For example, if FM1125 is configured to send an SMS, when Digital Input 1 reaches High level, with priority High and configured to generate event on both range enter and exit (figure 35), then the sent SMS is:

"2012/6/7 12:00:00 Digital Input 1"

| System | SMS Events | | | |
|----------------------|------------------|-------------------------------------|------------|------------------|
| Records | Description | Enable | SMS Number | SMS Text |
| GSM | Digital input 1 | <input checked="" type="checkbox"/> | 866666666 | Digital Input 1 |
| > GPRS | Digital input 2 | <input type="checkbox"/> | 866666666 | Digital Input 2 |
| > SMS | Digital input 3 | <input type="checkbox"/> | 866666666 | Digital Input 3 |
| > SMS Events | Digital input 4 | <input type="checkbox"/> | 866666666 | Digital Input 4 |
| > Operator list | Analog input 1 | <input type="checkbox"/> | 866666666 | Analog Input 1 |
| DataAcquisitionModes | Analog input 2 | <input type="checkbox"/> | 866666666 | Analog Input 2 |
| Features | Digital output 1 | <input type="checkbox"/> | 866666666 | Digital Output 1 |
| IO | Digital output 2 | <input type="checkbox"/> | 866666666 | Digital Output 2 |
| LVCAN | GNSS PDOP | <input type="checkbox"/> | 866666666 | GNSS PDOP |
| RS232 / RS485 | GNSS HDOP | <input type="checkbox"/> | 866666666 | GNSS HDOP |
| | External voltage | <input type="checkbox"/> | 866666666 | External Voltage |
| | GNSS power | <input type="checkbox"/> | 866666666 | GNSS Power |
| | Movement sensor | <input type="checkbox"/> | 866666666 | Movement Sensor |
| | Odometer value | <input type="checkbox"/> | 866666666 | Odometer Value |
| | GSM operator | <input type="checkbox"/> | 866666666 | GSM Operator |
| | Speed (km/h) | <input type="checkbox"/> | 866666666 | Speed |

Figure 33 Configured Digital Input 1 SMS event

The SMS Text field can be altered and any text can be entered. Maximum message length is 90 symbols (numbers, letters and symbols in ASCII, except for comma ",").



ATTENTION!

If FM1125 is in Deep Sleep mode and SMS event occurs with LOW priority (which does not wake up FM1125), then the device does not send the message. It is saved in device memory until it wakes up from Deep Sleep mode and GSM modem starts working normally. After it wakes up, all the messages that are saved in memory will be sent, but keep in mind that only 10 messages can be saved in memory – all other messages will not be saved, until there is room in device memory.

5.14.4.1 SMS events configuration

Scenarios

To configure SMS events for scenarios click scenarios window. Enabled scenarios will automatically appear near the SMS event window (figure 36). Note, that Green Driving can't work together with Over Speeding scenario – only one of them could be enabled. After enabling SMS events, different message texts can be written for different scenarios.

| System | SMS Events | | | |
|-----------------------------|-------------------------------------|--------------------------|------------|--|
| | Description | Enable | SMS Number | SMS Text |
| Records | Area of harvest | <input type="checkbox"/> | 866666666 | LVC Harvesting time |
| GSM | Mowing efficiency | <input type="checkbox"/> | 866666666 | LVC Area of harvest |
| > GPRS | Grain mown volume | <input type="checkbox"/> | 866666666 | LVC Mowing efficiency |
| > SMS | Grain moisture | <input type="checkbox"/> | 866666666 | LVC Grain Mown Volume |
| > SMS Events | Harvesting drum RPM | <input type="checkbox"/> | 866666666 | LVC Grain Moisture |
| > Operator list | Gap under harvesting drum | <input type="checkbox"/> | 866666666 | LVC Harvesting Drum RPM |
| DataAcquisitionModes | Security state flags | <input type="checkbox"/> | 866666666 | LVC Gap Under Harvesting Drum |
| Features | Tachograph total vehicle distance | <input type="checkbox"/> | 866666666 | LVC Security State Flags |
| IO | Trip distance | <input type="checkbox"/> | 866666666 | LVC Tacho Total Vehicle Distance |
| LVCAN | Tachograph vehicle speed | <input type="checkbox"/> | 866666666 | LVC Trip Distance |
| RS232 / RS485 | Tachograph driver card presence | <input type="checkbox"/> | 866666666 | LVC Tacho Vehicle Speed |
| | Driver 1 states | <input type="checkbox"/> | 866666666 | LVC Tacho Driver Card Presence |
| | Driver 2 states | <input type="checkbox"/> | 866666666 | LVC Drv1 States |
| | Driver 1 continuous driving time | <input type="checkbox"/> | 866666666 | LVC Drv2 States |
| | Driver 2 continuous driving time | <input type="checkbox"/> | 866666666 | LVC Drv1 Continuous Driving Time |
| | Driver 1 cumulative break time | <input type="checkbox"/> | 866666666 | LVC Drv2 Continuous Driving Time |
| | Driver 2 cumulative break time | <input type="checkbox"/> | 866666666 | LVC Drv1 Cumulative Break Time |
| | Driver 1 selected activity duration | <input type="checkbox"/> | 866666666 | LVC Drv2 Cumulative Break Time |
| | Driver 2 selected activity duration | <input type="checkbox"/> | 866666666 | LVC Drv1 Duration Of Selected Activity |
| | Driver 1 cumulative driving time | <input type="checkbox"/> | 866666666 | LVC Drv2 Duration Of Selected Activity |
| | Driver 2 cumulative driving time | <input type="checkbox"/> | 866666666 | LVC Drv1 Cumulative Driving Time |
| | EcoDriving | <input type="checkbox"/> | 866666666 | LVC Drv2 Cumulative Driving Time |
| | Overspeeding | <input type="checkbox"/> | 866666666 | Green Driving |
| | | | | OverSpeeding |

Figure 34 Scenarios SMS event configuration

When any of the scenarios events occurs, a text message will be sent to the predefined number.

Trip

In order to configure Trip SMS events click on Trip window. After enabling SMS Events (figure 37), trip event will be triggered and message sent, when Trip starts (GPS speed exceeds the speed in Start Speed (ex. 5 km/h) and when Trip stops, that is ignition is turned off longer then the time written in Ignition Off Timeout (ex. 60 seconds).

| | | | | |
|----------------------|-------------------------------------|--------------------------|-----------|---------------------------------------|
| > SMS Events | Gap under harvesting drum | <input type="checkbox"/> | 866666666 | LVC Gap Under Harvesting Drum |
| > Operator list | Security state flags | <input type="checkbox"/> | 866666666 | LVC Security State Flags |
| DataAcquisitionModes | Tachograph total vehicle distance | <input type="checkbox"/> | 866666666 | LVC Tacho Total Vehicle Distance |
| Features | Trip distance | <input type="checkbox"/> | 866666666 | LVC Trip Distance |
| IO | Tachograph vehicle speed | <input type="checkbox"/> | 866666666 | LVC Tacho Vehicle Speed |
| LVCAN | Tachograph driver card presence | <input type="checkbox"/> | 866666666 | LVC Tacho Driver Card Presence |
| RS232 / RS485 | Driver 1 states | <input type="checkbox"/> | 866666666 | LVC Dv1 States |
| | Driver 2 states | <input type="checkbox"/> | 866666666 | LVC Dv2 States |
| | Driver 1 continuous driving time | <input type="checkbox"/> | 866666666 | LVC Dv1 Continuous Driving Time |
| | Driver 2 continuous driving time | <input type="checkbox"/> | 866666666 | LVC Dv2 Continuous Driving Time |
| | Driver 1 cumulative break time | <input type="checkbox"/> | 866666666 | LVC Dv1 Cumulative Break Time |
| | Driver 2 cumulative break time | <input type="checkbox"/> | 866666666 | LVC Dv2 Cumulative Break Time |
| | Driver 1 selected activity duration | <input type="checkbox"/> | 866666666 | LVC Dv1 Duration Of Selected Activity |
| | Driver 2 selected activity duration | <input type="checkbox"/> | 866666666 | LVC Dv2 Duration Of Selected Activity |
| | Driver 1 cumulative driving time | <input type="checkbox"/> | 866666666 | LVC Dv1 Cumulative Driving Time |
| | Driver 2 cumulative driving time | <input type="checkbox"/> | 866666666 | LVC Dv2 Cumulative Driving Time |
| | EcoDriving | <input type="checkbox"/> | 866666666 | Green Driving |
| | Overspeeding | <input type="checkbox"/> | 866666666 | OverSpeeding |
| | Trip | <input type="checkbox"/> | 866666666 | Trip |

Figure 35 Trip Start/Stop SMS event configuration

Geofence

Geofence SMS event is triggered and message sent when the device exits and/or enters a configured Geofence zone. The Geofence zone must be configured to generate an event On Exit, On Enter or On Both (figure 38). If No Event is selected, then it is not possible to turn on SMS events. If several zones are created then SMS events can be turned on separately for each zone entering different text message.

| | | | |
|-----------------|--------------------------|-----------|-----------------|
| Geofence Zone 1 | <input type="checkbox"/> | 866666666 | Geofence Zone 1 |
| Geofence Zone 2 | <input type="checkbox"/> | 866666666 | Geofence Zone 2 |
| Geofence Zone 3 | <input type="checkbox"/> | 866666666 | Geofence Zone 3 |
| Geofence Zone 4 | <input type="checkbox"/> | 866666666 | Geofence Zone 4 |
| Geofence Zone 5 | <input type="checkbox"/> | 866666666 | Geofence Zone 5 |
| AutoGeofence | <input type="checkbox"/> | 866666666 | AutoGeofence |

Figure 36 Geofence SMS event configuration

AutoGeofence

SMS events for AutoGeofence are configured the same as in Geofence. AutoGeofence and its SMS event configuration is next to Geofence configuration (figure 39).

| | | | |
|-----------------|--------------------------|-----------|-----------------|
| Trip | <input type="checkbox"/> | 866666666 | Trip |
| Geofence Zone 1 | <input type="checkbox"/> | 866666666 | Geofence Zone 1 |
| Geofence Zone 2 | <input type="checkbox"/> | 866666666 | Geofence Zone 2 |
| Geofence Zone 3 | <input type="checkbox"/> | 866666666 | Geofence Zone 3 |
| Geofence Zone 4 | <input type="checkbox"/> | 866666666 | Geofence Zone 4 |
| Geofence Zone 5 | <input type="checkbox"/> | 866666666 | Geofence Zone 5 |
| AutoGeofence | <input type="checkbox"/> | 866666666 | AutoGeofence |

Figure 37 AutoGeofence SMS event configuration

I/O events

FM1125 sends SMS event message when a configured I/O property enters and/or exits its configured High/Low boundaries or Hysteresis event generation is chosen (Monitoring does not generate event, so SMS event could not be configured). Every IO element SMS event can be configured to send individual message to different numbers.

| System | SMS Events | | | |
|----------------------|------------------|-------------------------------------|------------|------------------|
| Records | Description | Enable | SMS Number | SMS Text |
| GSM | Digital input 1 | <input checked="" type="checkbox"/> | 866666666 | Digital Input 1 |
| > GPRS | Digital input 2 | <input type="checkbox"/> | 866666666 | Digital Input 2 |
| > SMS | Digital input 3 | <input type="checkbox"/> | 866666666 | Digital Input 3 |
| > SMS Events | Digital input 4 | <input type="checkbox"/> | 866666666 | Digital Input 4 |
| > Operator list | Analog input 1 | <input type="checkbox"/> | 866666666 | Analog Input 1 |
| DataAcquisitionModes | Analog input 2 | <input type="checkbox"/> | 866666666 | Analog Input 2 |
| Features | Digital output 1 | <input type="checkbox"/> | 866666666 | Digital Output 1 |
| IO | Digital output 2 | <input type="checkbox"/> | 866666666 | Digital Output 2 |
| LVCAN | GNSS PDOP | <input type="checkbox"/> | 866666666 | GNSS PDOP |
| RS232 / RS485 | GNSS HDOP | <input type="checkbox"/> | 866666666 | GNSS HDOP |
| | External voltage | <input type="checkbox"/> | 866666666 | External Voltage |
| | GNSS power | <input type="checkbox"/> | 866666666 | GNSS Power |
| | Movement sensor | <input type="checkbox"/> | 866666666 | Movement Sensor |
| | Odometer value | <input type="checkbox"/> | 866666666 | Odometer Value |
| | GSM operator | <input type="checkbox"/> | 866666666 | GSM Operator |
| | Speed (km/h) | <input type="checkbox"/> | 866666666 | Speed |

Figure 38 I/O SMS event configuration

5.15 I/O settings

When no I/O element is enabled, AVL packet comes with GPS information only. After enabling I/O element(s) AVL packet along with GPS information contains current value(s) of enabled I/O element.

| Permanent I/O elements (are always sent to server if enabled) | | | |
|--|-----------------------------------|-------|--|
| Nr. | Property Name | Bytes | Description |
| 1 | Digital Input Status 1 | 1 | Logic: 0 / 1 |
| 2 | Analog Input 1 | 2 | Voltage: mV, 0 – 30 V |
| 3 | GSM level | 1 | GSM signal level value in scale 1 – 5 |
| 4 | Speed | 2 | Value in km/h, 0 – xxx km/h |
| 5 | External Power Voltage | 2 | Voltage: mV, 0 – 30 V |
| 6 | GPS Power | 2 | States: 0 – short circ., 1 – connected. Parameter defines if GPS antenna is short circuit. All the time value will be sent 1. The only condition to get value 0, then antenna is damaged and short circuit. |
| 7 | Dallas Temperature | 4 | 10 * Degrees (°C), -55 - +115, if 3000 – Dallas error |
| 8 | iButton ID | 8 | iButton ID number |
| 9 | Data Mode | 1 | 0 – home on stop, 1 – home on move, 2 – roaming on stop, 3 – roaming on move, 4 – unknown on stop, 5 – unknown on move |
| 10 | Digital output 1 state | 1 | Logic: 0 / 1 |
| 11 | PDOP | 2 | Probability * 10; 0-500 |
| 12 | HDOP | 2 | Probability * 10; 0-500 |
| 13 | Odometer Value (Virtual Odometer) | 4 | Distance between two records: m |
| 14 | Sleep mode | 1 | 0 – not deep sleep mode, 1 – GPS sleep mode, 2 – deep sleep mode |
| 15 | Cell ID | 2 | GSM base station ID |
| 16 | Area Code | 2 | Location Area code (LAC), it depends on GSM operator. It provides unique number which assigned to a set of base GSM stations. Max value: 65536 |
| 14 | Movement | 1 | 0 – not moving, 1 – moving. |
| 18 | GSM operator Code | 4 | Currently used GSM Operator code |
| 19 | Battery Voltage | 4 | Shows battery Voltage in mV |
| 20 | Battery Current | 4 | Shows battery Current in mA |
| Eventual I/O elements (generate and send record to server only if appropriate conditions are met) | | | |
| Nr. | Property Name | Bytes | Description |
| 21 | Geofence zone 01 | 1 | Event: 0 – target left zone, 1 – target entered zone |
| 22 | Geofence zone 02 | 1 | Event: 0 – target left zone, 1 – target entered zone |
| 23 | Geofence zone 03 | 1 | Event: 0 – target left zone, 1 – target entered zone |
| 24 | Geofence zone 04 | 1 | Event: 0 – target left zone, 1 – target entered zone |

| | | | |
|----|---------------------|---|---|
| 25 | Geofence zone 05 | 1 | Event: 0 – target left zone, 1 – target entered zone |
| 26 | Auto Geofence | 1 | Event: 0 – target left zone, 1 – target entered zone |
| 27 | Trip | 1 | 1 – trip start, 0 – trip stop |
| 28 | Green driving type | 1 | 1 – harsh acceleration, 2 – harsh braking, 3 – harsh cornering |
| 29 | Green driving value | 1 | Depending on green driving type: if harsh acceleration or braking – g*100 (value 123 -> 1.23g), if harsh cornering – degrees (value in radians) |
| 30 | Over Speeding | 2 | At over speeding start km/h, at over speeding end km/h |



There are two types of operations with Permanent I/O elements: simple monitoring and event generating. Monitoring method is used when current I/O information needed with regular GPS coordinates. Event generating method is used when additional AVL packet is needed when current value of I/O exceeds predefined High and Low levels. I/O settings allow defining I/O event criteria.

| System | I/O | Property Input | <input type="checkbox"/> Enabled | Priority | Low Level | High Level | Generate Event | Averaging Constant |
|----------------------|-----|------------------|-------------------------------------|----------|-----------|------------|----------------|--------------------|
| Records | | Digital input 1 | <input checked="" type="checkbox"/> | Low | 0 | 0 | On Both | 10 |
| GSM | | Analog input 1 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| DataAcquisitionModes | | Analog input 2 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| Features | | Digital output 1 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | Digital output 2 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| IO | | GNSS PDOP | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | GNSS HDOP | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| LVCAN | | External voltage | <input checked="" type="checkbox"/> | Low | 10000 | 30000 | On Exit | 10 |
| RS232 / RS485 | | GNSS power | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | |
| | | Movement sensor | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | Odometer value | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | |
| | | GSM operator | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | |
| | | Speed (km/h) | <input checked="" type="checkbox"/> | Low | 0 | 5 | On Entrance | 60 |
| | | iButton ID | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | Mode | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | |
| | | GSM signal level | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | Deep sleep | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | |

Figure 39 I/O settings

Enabled or disabled field – allows enabling I/O element so it is added to the data packet and is sent to the server. By default all I/O element are disabled and FM1125 records only GPS coordinates.

Priority (AVL packet priority) can be low, high or panic. Regular packets are sent as Low priority records. When low priority event is triggered, FM1125 makes additional record with indication that the reason for that was I/O element change. When High priority is selected, module makes additional record with high priority flag and sends event packet immediately to the server by GPRS. Panic priority triggers same actions as high priority, but if GPRS fails, it sends AVL packet using SMS mode if SMS is **enabled in SMS settings**.

High and Low levels – define I/O value range. If I/O value enters or exits this range, FM1125 generates event. “Generate event” parameter defines when to generate event – when value enters defined range, exits it or both.

Averaging constant – it is an I/O event delay parameter. In some applications there is no need to generate events on every I/O range enter/exit immediately. Sometimes it is necessary to wait some time interval before event generating. Averaging constant allows setting I/O event delay (averaging). If I/O value is entering or leaving predefined range, it must have same value for Averaging constant time. 1 Averaging constant value equals about 30 milliseconds. In Deep Sleep mode there is no Averaging.



Note: I/O element’s “Movement sensor” Averaging constant is interpreted as Start Move Timeout in seconds (from 1 to 59).

Start Move Timeout – is a time interval required for movement sensor to be in the moving state, to consider vehicle as moving.

5.15.1 Monitoring

I/O monitoring starts after enabling I/O element and setting up I/O parameters as it is shown below:



| I/O Type | Status | Level | Low | High | Generate event | Averaging constant |
|------------------|-------------------------------------|-------|-----|------|----------------|--------------------|
| Digital input 1 | <input checked="" type="checkbox"/> | Low | 0 | 0 | On Both | 10 |
| Analog input 1 | <input type="checkbox"/> | Low | 0 | 0 | On Exit | 10 |
| Analog input 2 | <input type="checkbox"/> | Low | 0 | 0 | On Entrance | 10 |
| Digital output 1 | <input type="checkbox"/> | Low | 0 | 0 | On Both | 10 |
| Digital output 2 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | | | | Hysteresis | 10 |
| | | | | | On Change | 10 |
| | | | | | Monitoring | 10 |

Figure 40 I/O settings

5.15.2 Event Generating

Events happen when the value of enabled I/O intersects thresholds (enter, exit or on both) predefined by High and Low level thresholds. Table below defines all available values of I/O settings.

| Setting | Value |
|------------------|---|
| Priority | low, high |
| High level | maximum threshold |
| Low level | minimum threshold |
| Generate event | on interval enter, on interval exit, on both enter and exit |
| Average constant | 1 – 2 ³² (4 Bytes) |

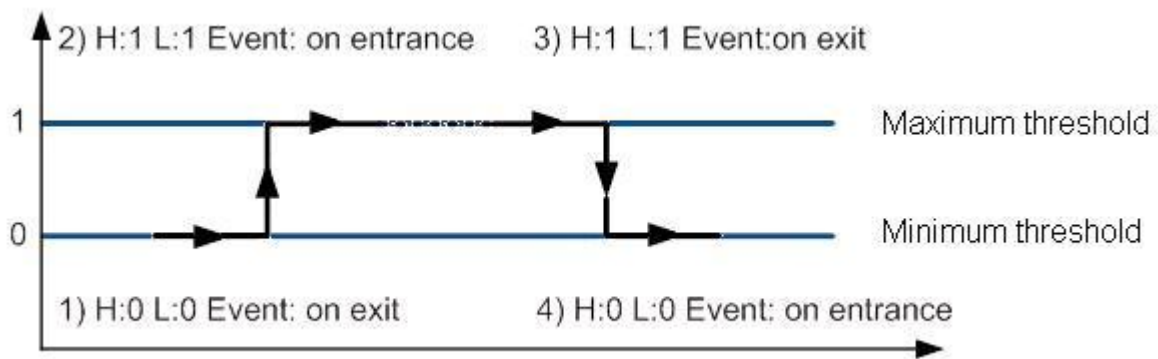


Figure 41 Digital Input event generation example

5.15.3 Hysteresis

| | | | | | | |
|------------------|-------------------------------------|-----|---|---|-------------|----|
| Digital input 1 | <input checked="" type="checkbox"/> | Low | 0 | 0 | On Both | 10 |
| Analog input 1 | <input type="checkbox"/> | Low | 0 | 0 | On Exit | 10 |
| Analog input 2 | <input type="checkbox"/> | Low | 0 | 0 | On Entrance | 10 |
| Digital output 1 | <input type="checkbox"/> | Low | 0 | 0 | Monitoring | 10 |
| | | | | | Hysteresis | 10 |

Figure 42 Hysteresis parameter configuration

I/O elements can generate events according to hysteresis algorithm. If I/O event operand “Hysteresis” is selected, events will be generated as it is shown in the illustration below (I/O speed is taken as I/O value example):

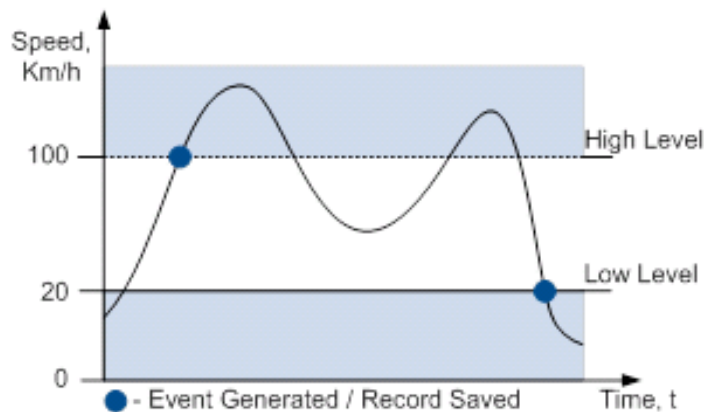


Figure 43 Event generation according hysteresis algorithm

6 SMS COMMAND LIST

Read chapter 5.11 to know how to construct a proper SMS message and send it to FM1125 device. All commands are case sensitive. While FM1125 operates in Deep Sleep mode and user tries to send SMS message it cannot arrive to FM1125 device, because GSM/GPRS module is disabled most of the time (wake up depends on Send Period parameter). FM1125 will receive the SMS when it wakes up (exits deep sleep mode).

6.1 SMS command list

| Command | Description | Response |
|---------------------|---|----------|
| getstatus | Modem Status information | Yes |
| getweektime | Current device time, Day of Week and amount of minutes passed since start of week | Yes |
| getops | List of currently available GSM operator | Yes |
| getcfgtime | Date and Time of last successful configuration | Yes |
| getgps | Current GPS data and time | Yes |
| cpureset | Reset CPU | No |
| resetprof | Reset all FLASH1 profile configuration to default profile | No |
| getver | Device / Modem / Code version information | Yes |
| getinfo | Device runtime system information | Yes |
| deleterecords | Delete all records saved on FLASH | No |
| getio | Readout digital inputs and outputs | Yes |
| readio # | Readout input value according entered ID, # - ID value | Yes |
| setdigout # Y1 | set digital outputs 0 – OFF, 1 – ON Y1 – timeout for DO1 | Yes |
| getparam # | Readout parameter value according entered ID. # - ID value. | Yes |
| setparam # # | Set parameter value according entered ID and Value. 1.# - ID value. 2.# - New Parameter Value | Yes |
| getparam 1271 X | X values can be 1,2,3. | Yes |
| flush #,#,#,#,#,#,# | Initiates all data sending to specified target server 1.# - IMEI 2.# - APN 3.# - LOGIN 4.# - PASS 5.# - IP 6.# - PORT 7.# - MODE (0-TCP/1-UDP) | No |
| readops # | 1 – send first 20 operator codes, 2 – send from 21 st to 40 th operator codes, 3 – send all other operator codes | |
| sn # | Static navigation, 1 – enable, 0 – disable | Yes |
| banlist | Banned operators information | Yes |
| crashlog | Device last information before unexpected reset | Yes |
| delete_all_sms | Deletes all SMS | No |

6.1.1 getstatus

| Response details | Description |
|------------------|--|
| Data Link | Indicate module connection to server at the moment: 0 – Not connected, 1 – connected |
| GPRS | Indicate if GPRS is available at the moment |
| Phone | Voice Call status: 0 – ready, 1 – unavailable, 2 – unknown, 3 – |

| | |
|---------|---|
| | ringing, 4 – call in progress, 5 – asleep |
| SIM | SIM Status: 0-ready, 1-pin, 2-puk, 3-pin2, 4-puk2 |
| OP | Connected to GSM Operator: numerical id of operator |
| Signal | GSM Signal Quality [0-5] |
| NewSMS | Indicate if new message received |
| Roaming | 0 – Home Network, 1 – roaming |
| SMSFull | SMS storage is full? 0 – ok, 1 – SMS storage full |
| LAC | GSM Tower Location Area Code |
| Cell ID | GSM Tower Cell ID Code |

Example: Data Link: 0 GPRS: 1 Phone: 0 SIM: 0 OP: 24602 Signal: 5 NewSMS: 0 Roaming: 0 SMSFull: 0 LAC: 1 Cell ID: 864

6.1.2 getweektime

| Response details | Description |
|------------------|--|
| Clock Sync | Indicates system clock synchronization status. 0 – System is not synchronized, 1 – System synchronized |
| DOW | Day Of Week – indicates current day of week starting from 1 – Monday, 2 – Tuesday, etc. |
| Time | Indicates current GMT time |
| WeekTime | Indicates time in minutes starting from Monday 00:00 GMT |

Example: Clock Sync: 1 DOW: 4 Time 12:58 Weektime: 6538

6.1.3 getops

| Response details | Description |
|------------------|--|
| LIST | Returns list of current available allowed operators. |

Example: (2,"LT BITE GSM","BITE","24602"),(3,"TELE2","TELE2","24603")

6.1.4 getcfgtime

| Response details | Description |
|------------------|---|
| Date/Time | Returns last performed configuration date and time. |

Example: Last Configuration was performed on: 2010.4.15 5:45:19

6.1.5 getgps

| Response details | Description |
|------------------|---|
| GPS | Indicates valid (1) or invalid (0) GPS data |
| Sat | Count of currently available satellites |
| Lat | Latitude (Last good Latitude) |
| Long | Longitude (Last good Longitude) |
| Alt | Altitude |
| Speed | Ground speed, km/h |
| Dir | Ground direction, degrees |

| | |
|------|------------------|
| Date | Current date |
| Time | Current GMT time |

Example: GPS:1 Sat:7 Lat:54.71473 Long:25.30304 Alt:147 Speed:0 Dir:77 Date: 2007/8/24
Time: 13:4:36

6.1.6 getver

| Response details | Description |
|------------------|---|
| Code Ver | Firmware version |
| Device IMEI | IMEI |
| Device ID | Device ID is used to detect by server which type of configuration to load |
| Bootloader Ver | Bootloader Version |
| Modem App Ver | Version of modem application (veiks: nuo 00.05.14) |
| Revision | Firmware revision |

Example: Code Ver:01.06.15 Rev:1 Device IMEI:353976010139156 Device ID:000001
Bootloader Ver: 01.09 Modem APP Ver:TM11Q_R_01.00.03.03_002

6.1.7 getinfo

| Response details | Description |
|------------------|---|
| INI | Device Initialization Time |
| RTC | RTC Time |
| RST | Restart Counter |
| ERR | Error Counter |
| SR | Number of Sent Records |
| BR | Number of broken records |
| CF | Profile CRC Fail counter |
| FG | Failed GPRS counter |
| FL | Failed link counter |
| UT | UPD Timeout counter |
| SMS | Sent SMS Counter |
| NOGPS | No GPS Timer |
| GPS | GPS receiver state. 0 – OFF, 1 – restarting, 2 – ON but no fix, 3 – ON and operational, 4 – sleep mode |
| SAT | Average satellites |
| RS | Reset Source Identification 1 – Low Power, 2 – W Watchdog, 3 – I Watchdog, 4 – Software reset, 5 – Power On, 6 – Pin Reset |
| MD | Data Mode state. 0 – Home and Stop, 1 – Home and Moving, 2 – Roaming and Stop, 3 – Roaming and Moving, 4 – Unknown and Stop, 5 – Unknown and Moving |
| RF | Records Found – number of records in the memory. |

Example: INI:2013/10/11 8:44 RTC:2013/10/11 8:59 RST:1 ERR:0 SR:0 BR:0 CF:0 FG:0 FL:0
UT:0 SMS:1 NOGPS:0:14 GPS:2 SAT:0 RS:3 MD:4 RF:0

6.1.8 getio

| Response details | Description |
|------------------|----------------------|
| DI# | Digital Input state |
| AIN# | Analog Input state |
| DO# | Digital Output state |

Example: DI1:0 AIN:0.0611 DO1:0

6.1.9 readio

| Response details | Description |
|------------------|-------------------|
| ID | I/O element ID |
| Value | I/O Element value |

Example: I/O ID:3 Value:0

6.1.10 setdigout # Y1

Sets digital outputs to ON or OFF state (for some time if needed). Value is written as a row for OUT1 values.

Example: 'setdigout 1 5' will set OUT1 to high level for 5 seconds.

6.1.11 getparam

Read parameter value. ID consists of 3 or 4 digits. Detailed list of parameters and IDs can be found in chapter number 8 "Parameter List"

Example: 'getparam 1245' command will request server IP address.

6.1.12 setparam

Sets new value for parameter. ID consists of 3 or 4 digits. Detailed list of parameters and IDs can be found in chapter number 8 "Parameter List"

Example: 'setparam 1245 127.0.0.1' will change configured IP address.

6.1.13. getparam 1271 X/212 X

X values can be 1,2,3.

If X = 1, Operator codes from 0-19 are read from configuration and sent via SMS.

If X = 2, Operator codes from 20-39 are read from configuration and sent via SMS.

If X = 3, Operator codes from 40-49 are read from configuration and sent via SMS.

If X = any other, Operator codes from 0-19 are read from configuration and sent via SMS.

6.1.14. setparam 1271 X/212 X

If X is from 0 to 49, X means index of operator code which has to be configured. Up to 20 operator codes may be configured in 1 SMS. Example: *Setparam 1271 16 24602,24603,24605*, here 16th, 17th and 18th operator codes are set. Note! Other operator codes are left unchanged in the configuration.

6.1.15 readops

Send from device Operator List.

1 – send first 20 operator codes, 2 – send from 21st to 40th operator codes, 3 – send all other operator codes.

6.1.16 flush #,#,#,#,#,#

Initiates all data sending by GPRS to specified target server. Comma separated parameters go as numbered:

- 1.# - IMEI
- 2.# - APN
- 3.# - GPRS LOGIN
- 4.# - GPRS PASSWORD
- 5.# - IP
- 6.# - PORT
- 7.# - MODE (0-TCP/1-UDP)

Parameters are separated by comma (no spaces needed). In case you don't need to enter parameter (Login/Pass) – do not put space, simply put comma and write next parameter.

Example: opa opa flush 353976012555151,banga,,,212.47.99.62,12050,0

| Response details | Description |
|----------------------------|--|
| FLUSH SMS Accepted | FLUSH SMS Accepted |
| # records found on FLASH | Number of records found on FLASH |
| Minimum Records to Send: # | Number of minimum saved records to send |
| GPRS Enabled: # | State of the GPRS connection, 0 – disabled; 1 – enabled |
| Time Sync: # | Indicates time synchronization on the device, 0 – not synchronized; 1 – synchronized |

Example: FLUSH SMS Accepted. 11 records found on FLASH. Minimum Records to Send: 1. GPRS Enabled: 1. Time Sync: 1.

6.1.17 sn

Enables or disables Static navigation. 1 – enable, 0 – disable.

6.1.18 banlist

Gives a list of all banned operators.

Example when no operators are banned: 0000.00s.0.000

6.1.19 crashlog

Gives the last information before the device has crashed for unexpected reasons. It is useful when the device acts unexpectedly or restarts for unexplained reasons.

Example if no unexpected reset: "Crash: "

Example if unexpected reset was detected: "Crash: 3051,3052,3053".

7 Debug mode

FM1125 is able to transmit its current state when connected to PC using USB cable. It is used to detect errors and provide information to possible solutions when operating as unexpected. Download Terminal from:

<http://avl1.teltonika.lt/Downloads/Software/Terminal.zip>.

After launching terminal choose baud rate 115200 and hardware control – none. Select COM port which is assigned to “Virtual COM Port”. Click on ‘Start Log’ button and save a new file. Then click ‘Connect’ to start receiving messages from FM1125.

Also you can log NMEA data directly. To get NMEA data, simply enter the following command into the command field: **.log_nmea:1\$0a**.

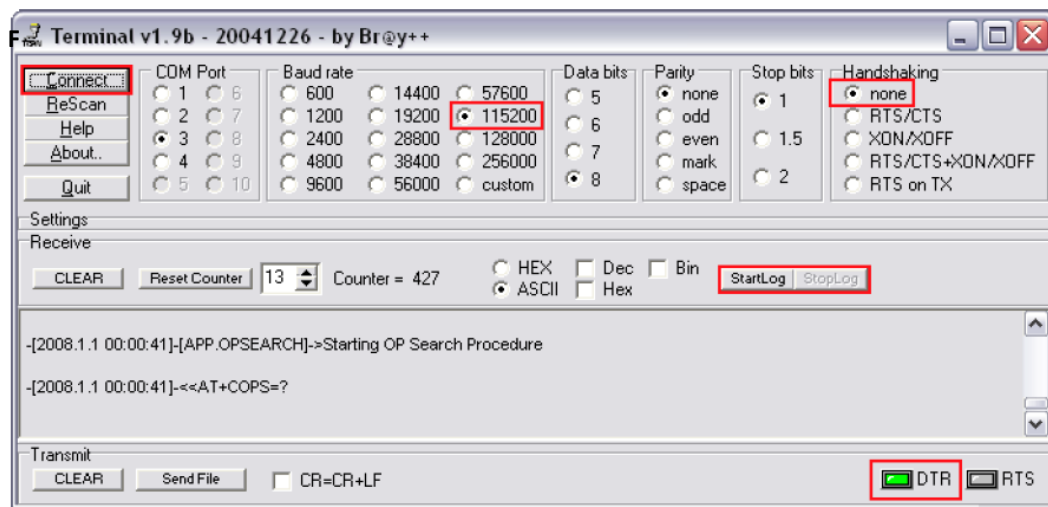


Figure 44 Terminal window for logging

8 Parameter List

8.1 Parameters value types

- S8 – Signed Char
- S8[n] – String of *n* Char
- U8 – Unsigned Char
- U16 – Unsigned Short
- S32 – Signed Integer
- U32 – Unsigned Integer
- U64 – Unsigned Long Long Integer

8.2 System parameters

8.2.1 Sleep Mode (ID=1000)

Device has two sleep modes: sleep and deep sleep mode. While sleep is disabled (value 0) module will never enter sleep mode, in sleep mode (value 1) module reduces level of power usage by turning GPS module to sleep, in deep sleep mode (value 2) module turns GPS module to sleep and switch GSM module off (note, that FM1125 do not receive SMS while in deep sleep).

| Minimum | Maximum | Recommended | Goes with (depends on) | Value |
|---------|---------|-------------|------------------------|-------|
|---------|---------|-------------|------------------------|-------|

| value | value | value | parameters | type |
|-------|-------|-------|------------|------|
| 0 | 2 | - | | U8 |

8.2.2 Sleep timeout (ID=200)

Sleep timeout is time after which FM1125 goes to sleep or deep sleep if other requirements are met. It is measured in minutes.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 | 3000 | - | | U8 |

8.2.3 Analog Input value range (ID=1001)

Analog input measuring resolution and range can be defined as 0...10V (value 0) or 1...30V (value 1).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | - | | U8 |

8.2.4 Stop Detection Source (ID=1002)

Device can operate and change its working mode according to motion detection source: ignition (value 0), movement sensor (value 1), GPS (value 2).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2 | - | | U8 |

8.2.5 Static Navigation (ID=1003)

When static navigation is enabled, FM1125 filters out GPS jumps, when it is not moving. When it is disabled, it does not make any changes to collected GPS data.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | 1 | | U8 |

8.2.6 Saving/Sending without time synchronization (ID=201)

When this feature is enabled (value = 1), then records can be saved and sent to server without time synchronization.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | 1 | | U8 |

8.2.7 GNSS System (ID=202)

This parameter sets Satellite System, available values: 0 - GNSS (all available); 1 – GPS only; 2 – GLONASS only

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2 | 0 | | U8 |

8.2.8 Ignition settings (ID=1004)

This parameter sets ignition source available values : 0 – Power voltage, 1 – Digital Input, 2 – Movement.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2 | 0 | | U8 |

8.2.9 High voltage level (ID=1005)

Sets high level of voltage if ignition settings is set to power voltage.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 30000 | 30000 | | U8 |

8.2.10 Low voltage level (ID=1006)

Sets low level of voltage if ignition settings is set to power voltage.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 30000 | 13000 | | U8 |

8.3 Records parameters

8.3.1 Sorting (ID=1010)

Record sorting parameter is responsible for record sorting order. Value of 0 arranging data starting from newest, while value of 1 arranging data starting from oldest.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | - | | U8 |

8.3.2 Active Data Link Timeout (ID=1011)

Defines for how many seconds device will keep connection to the server after successful data transfer while waiting for a new record.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 259200 | - | | U32 |

8.3.3 Server Response Timeout (ID=1012)

Defines time period (in seconds) for server response to sent records.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 | 300 | - | | U8 |



ATTENTION! Some GSM operators may disconnect the device from an active data link if the device doesn't send any data for a very long time, even if active data link timeout is set to maximum value. The amount of time that an operator keeps the link open depends solely on the operator. For example, if active data link timeout is set to maximum, 259200 seconds (72 hours), and the device sends data to server every 86400 seconds (24 hours), the operator might disconnect the link earlier and the device will have to connect to the server anew. This may cost extra, depending on the operator GPRS data charge. It is strongly recommended, when using active data link timeout, that data sending to the server should not be very rare (24 hours or more). If data sending is more frequent, then the operator will not disconnect the device from the server.

8.4 GSM parameters

8.4.1 GPRS content activation (ID=1240)

Parameter allows or does not allow GPRS usage. If GPRS is not allowed value is 0, if GPRS is allowed value is 1.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | - | APN Name (ID=1242) APN username (ID=1243) APN Password (ID=1244) | S8 |

8.4.2 APN Name (ID=1242)

Parameter defines GPRS Access Point Name.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|----------------|-------------------|---|------------|
| Empty | 32 char string | - | GPRS content activation (ID=1240) APN username (ID=1243) APN Password (ID=1244) | S8[32] |

8.4.3 APN username (ID=1243)

Parameter defines APN username. In case operator does not use username for login, value should be empty.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|----------------|-------------------|---|------------|
| Empty | 30 char string | - | GPRS content activation (ID=1240) APN Name (ID=1242) APN Password (ID=1244) | S8[30] |

8.4.4 APN Password (ID=1244)

Parameter defines APN password. In case operator does not use password for login, value should be empty.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|----------------|-------------------|---|------------|
| Empty | 30 char string | - | GPRS content activation (ID=1240) APN Name (ID=1242) APN username (ID=1243) | S8[30] |

8.4.5 Domain (ID=1245)

Parameter defines AVL data destination server IP address. Example: 212.47.99.62

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|----------------|-------------------|---|------------|
| 0 | 31 char string | - | GPRS content activation (ID=1240)Domain (ID=1245) | S8[16] |

8.4.6 Target Server Port (ID=1246)

Parameter defines AVL data destination server port number. Example: 12050

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| Empty | 65535 | - | GPRS content activation (ID=1240) Target Server Port (ID=1246) | U16 |

8.4.7 Protocol (ID=1247)

Parameter defines GPRS data transport protocol. Module can use TCP or UDP transport protocol to send data to server. For TCP protocol value is 0, for UDP protocol value is 1.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | - | GPRS content activation (ID=1240) | U8 |

8.4.8 SMS Login (ID=1252)

User login is used to ensure module security. Used in every SMS that is sent to device. Example: ba321

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| Empty | 5 char | - | SMS Password (ID=1253) | S8[5] |

8.4.9 SMS Password (ID=1253)

User password is used to ensure module security. Used in every SMS that is sent to device.
Example: ab123

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| Empty | 5 char | - | | S8[5] |

8.4.10 SMS data sending settings (ID=1250)

Parameter allows or does not allow sending AVL data using binary SMS. If SMS use is not allowed value is 0 and 1 if SMS use is allowed.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | - | SMS Data send week time schedule (ID=1273) | S8 |

8.4.11 SMS Data send week time schedule (ID=1273)

Parameter defines SMS data sending according to week time schedule. This parameter is used to set data sending on selected week days and hours. Minimum time step is 10 minutes.

Example value: 7F,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF

For more information read 8.5.1.4 "Schedule parameter format".

8.4.12 Authorized phone numbers (ID=1260-1270)

If at least one number is entered then only those number can send messages to device. Number must be entered without "+" or "00".

Example: 37060012346

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 digit | 16 digits | - | | S8[17] |

If SMS data sending is enabled (ID=1260) first value in a list is server GSM number. The SMS with 24 coordinates is sent to this number.

8.4.13 SMS Event PreDefined Numbers (ID=150-159)

In this field are written GSM numbers, to which will be sent "Event SMS" text message. Number must be entered without "+" or "00".

Example: 37060012346

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 digit | 16 digits | - | | S8[17] |

8.4.14 Operator List (ID=1271 X)

Parameter defines operator list. According to this list module selects operating profile. GSM operator codes are comma separated. First in a list is *Home Operator Code*, then Preferred Roaming Operator Codes are written.

X defines starting position that is changed: If X is from 0 to 49, X means index of operator code which has to be configured. Up to 20 operator codes may be configured in 1 SMS. Example: `setparam 1271 16 24602,24603,24605`

Here 16th, 17th and 18th operator codes are set. Note! Other operator codes are left unchanged in the configuration.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| Empty | 7 digits | - | | U32 |

8.5 Data Acquisition Modes parameters

8.5.1 Home Network GSM operator code “Vehicle on STOP” parameters

8.5.1.1 Min Period (ID=1540)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2592000 | - | | U32 |

8.5.1.2 Min Saved Records (ID=1543)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1544).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 | 255 | 1 | GPRS Week Time (ID=1545) | U8 |

8.5.1.3 Send Period (ID=1544)

This parameter indicates frequency (time interval in seconds) of sending data to server.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Saved Records (ID=1543) GPRS Week Time (ID=1545) | U32 |

8.5.1.4 GPRS Week Time (ID=1545)

This parameter manages when it is allowed to open GPRS context. When module starts it is prohibited to open the context. When modem's GPRS context is closing (for example changing network) it is allowed to open it only at a defined time. It is possible to allow connections every 10 minutes up to once per day.

Example value: 7F,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF,FF

Schedule parameter format:

Time is defined as 19 byte array. First byte of array defines week days; the rest 18 bytes define timestamps with 10 minute interval. In first byte, first bit (LSB) defines if module should connect to GPRS (send SMS) on Monday, second bit – on Tuesday and so on up to seventh bit – which means Sunday. Eighth bit (MSB) is not used. If bits value is 0 then device is not allowed to open GPRS context, but if it is already open – does not close it. If value is 1 it will work as day minutes are defined in rest of the bytes. Day's minutes are defined by 18 bytes (144 bits). Every n^{th} bit (beginning from the first bit (LSB) and ending 18 bytes 8th bit (MSB)) indicates every 10th minute of the day (day has 1440 minutes).

Sample: GPRS will be allowed on Monday to Friday at 8:00 and 16:00 GMT. The following value should be configured:

00011111 00000000 00000000 00000000 00000000 00000000 00000000 00000001 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000 00000000

Red bits indicate that GPRS will be allowed every day except Saturdays and Sundays. Blue bits indicate 480 and 720 minutes (480min = 8h and 720min = 16h). So the parameter value should be: 1F,00,00,00,00,00,00,01,00,00,00,00,00,01,00,00,00,00,00

It should be sent as UTF8 encoded string.

8.5.2 Home Network GSM operator code "Vehicle MOVING" parameters

8.5.2.1 Min Period (ID=1550)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Distance (ID=1551) Min Angle (ID=1552) GPRS Week Time (ID=1555) | U32 |

8.5.2.2 Min Distance (ID=1551)

This parameter indicates distance in meters in order to acquire new record. Record is stored when the distance between previous records is greater than parameters value. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 65535 | - | Min Period (ID=1550) Min Angle (ID=1552) GPRS Week Time (ID=1555) | U32 |

8.5.2.3 Min Angle (ID=1552)

This parameter indicates angle in degrees in order to acquire new record. If angle difference between last recorded coordinate and current position is greater than defined value, new record is stored. This parameter is operational, when speed is higher than 10km/h. If value is 0 it means no records by min angle will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 180 | - | Min Period (ID=1550) Min Distance (ID=1551) | U16 |

| | | | | |
|--|--|--|---------------------------------|--|
| | | | GPRS Week Time (ID=1555) | |
|--|--|--|---------------------------------|--|

8.5.2.4 Min Speed (ID=1556)

This parameter indicates speed difference in order to acquire new record. If speed difference between last recorded coordinate and current position is greater than defined value, new record is stored. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 255 | 10 | Min Period (ID=1550) Min Distance (ID=1551) Min Angle (ID=1552) Min Speed Source (ID=1557)GPRS Week Time (ID=1555) | U16 |

8.5.2.5 Min Speed Source (ID=1557)

This parameter defines Source for speed difference calculation: 0 – GPS, 1 – LVCAN

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | 0 | Min Period (ID=1550) Min Distance (ID=1551) Min Angle (ID=1552) Min Speed (ID=1556)GPRS Week Time (ID=1555) | U8 |

8.5.2.6 Min Saved Records (ID=1553)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1554).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 1 | 255 | 1 | Min Period (ID=1550) Min Distance (ID=1551) Min Angle (ID=1552) GPRS Week Time (ID=1555) | U8 |

8.5.2.7 Send Period (ID=1554)

This parameter indicates frequency (time interval in seconds) of sending data to server.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2592000 | - | GPRS Week Time (ID=1555) | U32 |

8.5.2.8 GPRS Week Time (ID=1555)

Read 8.5.1.4.

8.5.3 Roaming Network GSM operator code “Vehicle on STOP” parameters

8.5.3.1 Min Period (ID=1560)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2592000 | - | | U32 |

8.5.3.2 Min Saved Records (ID=1563)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1564).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 | 255 | 1 | GPRS Week Time (ID=1565) | U8 |

8.5.3.3 Send Period (ID=1564)

This parameter indicates frequency (time interval in seconds) of sending data to server.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Saved Records (ID=1563) GPRS Week Time (ID=1565) | U32 |

8.5.3.4 GPRS Week Time (ID=1565)

Read chapter 8.5.1.4.

8.5.4 Roaming Network GSM operator code “Vehicle MOVING” parameters

8.5.4.1 Min Period (ID=1570)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Distance (ID=1571) Min Angle (ID=1572) GPRS Week Time (ID=1575) | U32 |

8.5.4.2 Min Distance (ID=1571)

This parameter indicates distance in meters in order to acquire new record. Record is stored when the distance between previous records is greater than parameter's value. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 65535 | - | Min Period (ID=1570) Min Angle (ID=1572) GPRS Week Time (ID=1575) | U32 |

8.5.4.3 Min Angle (ID=1572)

This parameter indicates angle in degrees in order to acquire new record. If angle difference between last recorded coordinate and current position is greater than defined value, new record is stored. This parameter is operational, when speed is higher than 10km/h. If value is 0 it means no records by min angle will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
|---------------|---------------|-------------------|-----------------------------------|------------|

| | | | | |
|---|-----|---|---|-----|
| 0 | 180 | - | Min Period (ID=1570) Min Angle (ID=1572) GPRS Week Time (ID=1575) | U16 |
|---|-----|---|---|-----|

8.5.4.4 Min Speed (ID=1576)

This parameter indicates speed difference in order to acquire new record. If speed difference between last recorded coordinate and current position is greater than defined value, new record is stored. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 255 | 10 | Min Period (ID=1570) Min Distance (ID=1571) Min Angle (ID=1572) Min Speed Source (ID=1577) GPRS Week Time (ID=1575) | U16 |

8.5.4.5 Min Speed Source (ID=1577)

This parameter defines Source for speed difference calculation: 0 – GPS, 1 – LVCAN

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | 0 | Min Period (ID=1570) Min Distance (ID=1571) Min Angle (ID=1572) Min Speed (ID=1576) GPRS Week Time (ID=1575) | U8 |

8.5.4.6 Min Saved Records (ID=1573)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1574).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 1 | 255 | 1 | Min Period (ID=1570) Min Distance (ID=1571) Min Angle (ID=1572) GPRS Week Time (ID=1575) | U8 |

8.5.4.7 Send Period (ID=1574)

This parameter indicates frequency (time interval in seconds) of sending data to server.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Saved Records (ID=1573) GPRS Week Time (ID=1575) | U32 |

8.5.4.8 GPRS Week Time (ID=1575)

Read chapter 8.5.1.4.

8.5.5 Unknown Network GSM operator code “Vehicle on STOP” parameters

8.5.5.1 Min Period (ID=1580)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2592000 | - | | U32 |

8.5.5.2 Min Saved Records (ID=1583)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1584).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 1 | 255 | 1 | GPRS Week Time (ID=1585) | U8 |

8.5.5.3 Send Period (ID=1584)

This parameter indicates frequency (time interval in seconds) of sending data to server.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Saved Records (ID=1583) GPRS Week Time (ID=1585) | U32 |

8.5.5.4 GPRS Week Time (ID=1585)

Read chapter 8.5.1.4.

8.5.6 Unknown Network GSM operator code “Vehicle MOVING” parameters

8.5.6.1 Min Period (ID=1590)

This parameter indicates time interval in seconds in order to acquire new record. If value is 0 it means no records by min period will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Distance (ID=1591) Min Angle (ID=1592) GPRS Week Time (ID=1595) | U32 |

8.5.6.2 Min Distance (ID=1591)

This parameter indicates distance in meters in order to acquire new record. Record is stored when the distance between previous records is greater than parameter’s value. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 65535 | - | Min Period (ID=1590) | U32 |

| | | | | |
|--|--|--|---|--|
| | | | Min Angle (ID=1592) GPRS Week Time (ID=1595) | |
|--|--|--|---|--|

8.5.6.3 Min Angle (ID=1592)

This parameter indicates angle in degrees in order to acquire new record. If angle difference between last recorded coordinate and current position is greater than defined value, new record is stored. This parameter is operational, when speed is higher than 10km/h. If value is 0 it means no records by min angle will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 180 | - | Min Period (ID=1590) Min Distance (ID=1591) GPRS Week Time (ID=1595) | U16 |

8.5.6.4 Min Speed (ID=1596)

This parameter indicates speed difference in order to acquire new record. If speed difference between last recorded coordinate and current position is greater than defined value, new record is stored. If value is 0 it means no records by min distance will be saved.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 255 | 1 | Min Period (ID=1590) Min Distance (ID=1591) Min Angle (ID=1592) Min Speed Source (ID=1597) GPRS Week Time (ID=1595) | U16 |

8.5.6.5 Min Speed Source (ID=1597)

This parameter defines Source for speed difference calculation: 0 – GPS, 1 – LVCAN

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | 0 | Min Period (ID=1590) Min Distance (ID=1591) Min Angle (ID=1592) Min Speed (ID=1596) GPRS Week Time (ID=1595) | U8 |

8.5.6.6 Min Saved Records (ID=1593)

This parameter defines minimum number of records in one data packet that can be sent to server. It has higher priority than Data Send Period (ID=1594).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 1 | 255 | 1 | Min Period (ID=1590) Min Distance (ID=1591) Min Angle (ID=1592) GPRS Week Time (ID=1595) | U8 |

8.5.6.7 Send Period (ID=1594)

This parameter indicates frequency (time interval in seconds) of sending data to server. In order to send data to server GPRS parameters must be enabled

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 2592000 | - | Min Saved Records (ID=1593) GPRS Week Time (ID=1595) | U32 |

8.5.6.8 GPRS Week Time (ID=1595)

Read chapter 8.5.1.4.

8.6 Features Parameters

8.6.1 Digital Output No.1 usage scenarios (ID=1600)

Device can operate in its scenario according to selected value: No Scenario for Digital No.1 selected (value 0); Green Driving selected (value 1), Overspeeding selected (value 2).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2 | - | | U8 |

8.6.1 Max Acceleration Force (ID=1602)

It is max allowed acceleration force which can be reached while accelerating without triggering harsh acceleration event.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0.25 | 0.85 | 0.25 | Digital Output No.1 usage scenarios (ID=1600) | Float |

8.6.2 Max Braking Force (ID=1603)

It is max allowed braking force which can be reached while braking without triggering harsh braking event.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0.25 | 0.85 | 0.35 | Digital Output No.1 usage scenarios (ID=1600) | Float |

8.6.3 Max Angular Velocity (ID=1604)

It is max allowed cornering angle which can be reached while cornering without triggering harsh cornering event.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0.1 | 1.0 | - | Digital Output No.1 usage scenarios (ID=1600) | U16 |

8.6.4 Max allowed Speed (ID=1605)

It is max allowed speed which can be reached. If this value exceeded Over speeding event will occur.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 260 | - | Digital Output No.1 usage scenarios (ID=1600) | U16 |

8.6.5 Trip (ID=1280)

This parameter enables ability to detect START and STOP of the trip.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | - | | U8 |

8.6.6 Start Speed (ID=1281)

This parameter represents speed, which is detected as minimum speed to indicate TRIP START and generate event.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 255 | - | Trip (ID=1280) | U8 |

8.6.7 Ignition Off Timeout (ID=1282)

This parameter represents timeout to wait if ignition is off in order to detect TRIP STOP and generate event.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 65535 | - | Trip (ID=1280) | U16 |

8.6.8 Trip Continuous distance counting (ID=1283)

For this feature I/O#11 ODOMETER must be enabled. If I/O ODOMETER is enabled, and Continuous distance counting variable is set to Continuous (value 1), TRIP distance is going to be counted continuously (from TRIP start to TRIP stop) and shown as I/O ODOMETER value.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | - | Trip (ID=1280) I/O#11 – Odometer (ID = 1410-1415) | U8 |

8.6.9 Geofencing

In this chapter it is explained how to get all parameters for the first Geofence zone (all ID numbers are for the 1st zone). And at the end of the chapter (part 8.6.9) is presented a table with the IDs of all the rest Geofence zones.

8.6.9.1 Frame border (ID=1020)

Geofence border thickness, measured in meters.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1000000 | 1000 | All Geofencing parameters | U32 |

8.6.9.2 Geofence Zone #1 Shape (ID=1030)

Geofence shape parameter can be: circle – value 0; rectangle – value 1.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | - | All Geofencing parameters | U8 |

8.6.9.3 Geofence Zone #1 Priority (ID=1031)

Parameter defines Geofence priority: 0 is low, 1 – high, 2 – panic;

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 2 | - | All Geofencing parameters | U8 |

8.6.9.4 Geofence Zone #1 Generate Event (ID=1032)

Generate event on:

- a) No event – value 0
- b) On entering zone – value 1;
- c) On exiting zone – value 2;
- d) On both – value 3;

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 3 | - | All Geofencing parameters | U8 |

8.6.9.5 Geofence Zone #1 Longitude (X1) (ID=1033)

Parameter has two meanings dependent on zone shape. If shape is a rectangle, then ID=1033 is left down corner X coordinate. If shape is a circle, then ID=1033 is center of that circle X coordinate.

Sample value: 25.30528

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| -180 | 180 | - | All Geofencing parameters | Float |

8.6.9.6 Geofence Zone #1 Latitude (Y1) (ID=1034)

Parameter has two meanings dependent on zone shape. If shape is a rectangle, then ID=1034 is left down corner Y coordinate. If shape is a circle, then ID=1034 is center of that circle Y coordinate.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| -90 | 90 | - | All Geofencing parameters | Float |

8.6.9.7 Geofence Zone #1 Longitude (X2) (ID=1035)

Parameter has two meanings depending on zone shape. If shape is a rectangle, then ID=1035 is right upper corner X coordinate. If shape is a circle, then ID=1035 is radius of circle with center of ID=1033 and ID=1034.

For rectangle:

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| -180 | 180 | - | All Geofencing parameters | Float |

For circle:

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1000000 | 1000 | All Geofencing parameters | Float |

8.6.9.8 Geofence Zone #1 Latitude (Y2) (ID=1036)

If shape is rectangular, then ID=1036 is right upper corner Y coordinate. If shape circle, ID=1036 is not used.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| -90 | 90 | - | All Geofencing parameters | Float |

Other 4 GeoFence zone's parameters have the same logic as shown in GeoFence Zone #1.

| GeoFence Zone Number | Geofence Zone's parameters |
|----------------------|----------------------------|
| 1 | 1030-1036 |
| 2 | 1040-1046 |
| 3 | 1050-1056 |
| 4 | 1060-1066 |
| 5 | 1070-1076 |

8.6.10 AutoGeofencing

8.6.10.1 Enable/Disable (ID=1101)

Enable – value 1; disable – value 0;

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 1 | 1 | | U8 |

8.6.10.2 Activation Timeout (ID=1102)

Parameter represents AutoGeofencing activation timeout in seconds.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|-----------------------------------|------------|
| 0 | 65535 | 60 | Enable/Disable (ID=1101) | U16 |

8.6.10.3 Deactivate by (ID=1100)

Parameter defines Autogeofence deactivation source. Value 1 is dedicated for attached iButton, value 0 – for Ignition.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 1 | - | Enable/Disable (ID=1101) iButton List (ID=1610-1659) | U8 |

8.6.10.4 AutoGeofence event Priority (ID=1103)

Parameter defines AutoGeofence event priority: 0 is low, 1 – high;

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 1 | 1 | Enable/Disable (ID=1101) AutoGeofence event generating (ID=1104) | U8 |

8.6.10.5 AutoGeofence event generating (ID=1104)

Generate event: 0 – no event, 1 – on entering zone; 2 – on exiting zone; 3 – on both;

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 3 | 2 | Enable/Disable (ID=1101) AutoGeofence event Priority (ID=1103) | U8 |

8.6.10.6 Radius (ID=1105)

Parameter represents radius of circle with center device coordinates after activating AutoGeofence feature.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|---|------------|
| 0 | 1000000 | 100 | Enable/Disable (ID=1101) Deactivate by (ID=1100) | U32 |

8.6.11 iButton List (ID=1610-1659)

Read 5.4.4.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|----------------------|-------------------|-----------------------------------|------------|
| 0 | FFFFFFFF FFFFFFFF | - | Deactivate by (ID=1100) | U64 |

8.7 I/O parameters

I/O properties are additional data sources which are recorded along with usual GPS data.

8.7.1 I/O#1 property parameter (ID=1300)

Parameter defines I/O property value. Possible values: enabled (1), disabled (0).

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 1 | - | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) | S8 |

| | | | | |
|--|--|--|--|--|
| | | | I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | |
|--|--|--|--|--|

8.7.2 I/O#1 priority (ID=1301)

Parameter defines I/O property type of priority: 0 is disabled, 1 – low, 2 – high, 3 - panic.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 3 | 0 | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | S8 |

8.7.3 I/O#1 High level (ID=1302)

Parameter defines high value of triggered I/O property. This parameter is used to set thresholds for I/O properties to generate events.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| -2147483647 | 2147483647 | 1 | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | S32 |

8.7.4 I/O#1 Low level (ID=1303)

Parameter defines low value of triggered I/O property. This parameter is used to set thresholds for I/O properties to generate events.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| -2147483647 | 2147483647 | 0 | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | S32 |

8.7.5 I/O#1 logic operand (ID=1304)

Parameter defines when event is sent: 0 – on range exit, 1 – on range entrance, 2 – both, 3 – monitoring, 4 – hysteresis, 5 – on changes.

| Minimal value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 5 | 3 | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | S8 |

8.7.6 I/O#1 averaging length (ID=1305)

Parameter defines I/O property sample length to average. If no averaging needed default value is 1.

| Minimum value | Maximum value | Recommended value | Goes with (depends on) parameters | Value type |
|---------------|---------------|-------------------|--|------------|
| 0 | 2147483647 | 1 | I/O#1 property parameter (ID=1300) I/O#1 priority (ID=1301) I/O#1 High level (ID=1302) I/O#1 Low level (ID=1303) I/O#1 logic operand (ID=1304) I/O#1 averaging length (ID=1305) | S32 |

Other I/O property elements can be configured in same logic. All I/O element parameters are listed in the next table.

| I/O Element Number | I/O element parameters |
|----------------------------|------------------------|
| I/O#0 – Digital input 1 | 1300 – 1305 |
| I/O#3 – Analog input | 1330 – 1335 |
| I/O#4 – Digital output 1 | 1340 – 1345 |
| I/O#6 – PDOP | 1360 – 1365 |
| I/O#7 – HDOP | 1370 – 1375 |
| I/O#8 – External Voltage | 1380 - 1385 |
| I/O#9 – GPS power | 1390 – 1395 |
| I/O#10 – Movement | 1400 – 1405 |
| I/O#11 – Odometer value | 1410 – 1415 |
| I/O#12 – GSM operator | 1420 – 1425 |
| I/O#13 – Speed | 1430 – 1435 |
| I/O#14 – iButton ID | 1440 – 1445 |
| I/O#15 – Working Mode | 1450 – 1455 |
| I/O#16 – GSM Signal | 1460 – 1465 |
| I/O#17 – Deep Sleep | 1470 – 1475 |
| I/O#18 – Cell ID | 1480 – 1485 |
| I/O#19 – Area Code | 1490 – 1495 |
| I/O#20 – Temperature | 1500 – 1505 |
| I/O#21 – Battery voltage | 1530 – 1535 |
| I/O#22 – Battery current | 1110 – 1115 |
| I/O#23 – Ignition | 1120 - 1125 |
| I/O#24 – RFID | 1160 – 1165 |
| I/O#25 – LLS Fuel Level 1 | 1720 – 1725 |
| I/O#26 – LLS Temperature 1 | 1730 – 1735 |
| I/O#27 – LLS Fuel Level 2 | 1740 – 1745 |
| I/O#28 – LLS Temperature 2 | 1750 – 1755 |
| I/O#29 – LLS Fuel level 3 | 1760 – 1765 |
| I/O#30 – LLS Temperature 3 | 1770 – 1775 |
| I/O#31 – LLS Fuel Level 4 | 1780 – 1785 |
| I/O#32 – LLS Temperature 4 | 1790 – 1795 |
| I/O#33 – LLS Fuel Level 5 | 1800 – 1805 |
| I/O#34 – LLS Temperature 5 | 1810 – 1815 |
| I/O#35 – Reserved IO | X |
| I/O#36 – Reserved IO | X |
| I/O#37 – Reserved IO | X |

LVCAN property elements can be configured in same logic. All LVCAN element parameters are listed in the next table

| LVCAN parameter | LVCAN param. number |
|-----------------------------------|---------------------|
| Program number | 2000 – 2004 |
| Module ID | 2010 – 2014 |
| Engine worktime | 2020 – 2024 |
| Engine worktime (counted) | 2030 – 2034 |
| Total mileage | 2040 – 2044 |
| Total mileage (counted) | 2050 – 2054 |
| Fuel consumed | 2060 – 2064 |
| Fuel consumed (counted) | 2070 – 2074 |
| Fuel level (%) | 2080 – 2085 |
| Fuel level (liters) | 2090 – 2095 |
| Fuel rate | 2100 – 2105 |
| AdBlue level (%) | 2110 – 2115 |
| AdBlue level (liters) | 2120 – 2125 |
| Engine RPM | 2130 – 2135 |
| Engine load | 2140 – 2145 |
| Engine temperature | 2150 – 2155 |
| Accelerator pedal position | 2160 – 2165 |
| Vehicle speed | 2170 – 2175 |
| Axle 1 load | 2180 – 2185 |
| Axle 2 load | 2190 – 2195 |
| Axle 3 load | 2200 – 2205 |
| Axle 4 load | 2210 – 2215 |
| Axle 5 load | 2220 – 2225 |
| Control state flags | 2230 – 2234 |
| Agricultural machinery flags | 2240 – 2244 |
| Harvesting time | 2250 – 2254 |
| Area of harvest | 2260 – 2264 |
| Mowing efficiency | 2270 – 2275 |
| Grain mown volume | 2280 – 2284 |
| Grain moisture | 2290 – 2295 |
| Harvesting drum RPM | 2300 – 2305 |
| Gap under harvesting drum | 2310 – 2315 |
| Security state flags | 2320 – 2324 |
| Tachograph total vehicle distance | 2330 – 2334 |
| Trip distance | 2340 – 2344 |
| Tachograph vehicle speed | 2350 – 2355 |
| Tachograph driver card presence | 2360 – 2364 |
| Driver 1 state | 2370 – 2374 |
| Driver 2 state | 2380 – 2384 |
| Driver 1 continuous driving time | 2390 – 2394 |
| Driver 2 continuous driving | 2400 – 2404 |

| | |
|-------------------------------------|-------------|
| time | |
| Driver 1 cumulative break time | 2410 – 2414 |
| Driver 2 cumulative break time | 2420 – 2424 |
| Driver 1 selected activity duration | 2430 – 2434 |
| Driver 2 selected activity duration | 2440 – 2444 |
| Driver 1 cumulative driving time | 2450 – 2454 |
| Driver 2 cumulative driving time | 2460 – 2464 |

RS-232 and RS-485 Param ID's:

| RS-232 description | Param. ID |
|-----------------------------|-----------|
| RS232 Mode | 1660 |
| RS232 Baudrate | 1661 |
| RS232 Parity | 1662 |
| RS232 Prefix 1 | 1663 |
| RS232 Prefix 2 | 1664 |
| RS232 Prefix 3 | 1665 |
| RS232 Garmin Ping Filter | 1666 |
| RS232 Garmin Unicode Filter | 1667 |

| RS-485 description | Param. ID |
|----------------------|-----------|
| RS485 Mode | 1690 |
| RS485 Baudrate | 1691 |
| LLS1 Address [0-254] | 1700 |
| LLS2 Address [0-254] | 1701 |
| LLS3 Address [0-254] | 1702 |
| LLS4 Address [0-254] | 1703 |
| LLS5 Address [0-254] | 1704 |

SMS event configuration

8.7.7 I/O#1 element SMS event configuration (ID=100)

Command sets SMS warning on I/O#1 element.

SMS Format: setparam X Y,W,Z

X – ID

Y – Enable/Disable (1/0)

W – Telephone number INDEX (See **8.4.18 SMS Event Predefined Numbers** paragraph, ID 150 – INDEX 0; ID151 – INDEX 1, ...)

Z – SMS Text

Example: “setparam 3000 1,5,Digital Input 1 Event!”

Other I/O element SMS events can be configured in same logic. All I/O element SMS event IDs are listed in the next table.

| Element name (default SMS Event Text) | ID |
|---------------------------------------|-----|
| Digital input 1 | 100 |
| Analog input 1 | 103 |
| Digital output 1 | 104 |
| GNSS PDOP | 106 |
| GNSS HDOP | 107 |
| External voltage | 108 |
| GNSS power | 109 |
| Movement | 110 |
| Odometer | 111 |
| GSM operator | 112 |
| Speed | 113 |
| iButton ID | 114 |
| Mode | 115 |
| GSM signal level | 116 |
| DeepSleep | 117 |
| GSM Cell ID (CID) | 118 |
| GSM Area Code (LAC) | 119 |
| Dallas temperature | 120 |
| Battery voltage | 123 |
| Battery charging current | 124 |
| Ignition | 125 |
| Reserved IO | 126 |
| Reserved IO | 127 |
| Reserved IO | 128 |
| Green driving | 137 |
| Overspeeding | 138 |
| Authorized Driving | 139 |
| Immobilizer | 140 |
| Trip | 141 |
| Geofence 1 | 142 |
| Geofence 2 | 143 |
| Geofence 3 | 144 |
| Geofence 4 | 145 |
| Geofence 5 | 146 |
| AutoGeofence | 147 |
| RFID | 250 |
| LLS Fuel Level 1 | 251 |
| LLS Temperature 1 | 252 |
| LLS Fuel Level 2 | 253 |
| LLS Temperature 2 | 254 |
| LLS Fuel Level 3 | 255 |
| LLS Temperature 3 | 256 |
| LLS Fuel Level 4 | 257 |
| LLS Temperature 4 | 258 |
| LLS Fuel Level 5 | 259 |

| LVCAN SMS Event | ID |
|-----------------------------------|-----|
| Vehicle speed | 129 |
| Accelerator pedal position | 130 |
| Fuel consumed | 131 |
| Fuel level (liters) | 132 |
| Engine RPM | 133 |
| Total mileage | 134 |
| Fuel level (%) | 135 |
| Program number | 136 |
| Module ID | 210 |
| Engine worktime | 211 |
| Engine worktime(counted) | 212 |
| Total mileage (counted) | 213 |
| Fuel consumed (counted) | 214 |
| Fuel rate | 215 |
| AdBlue level (%) | 216 |
| AdBlue level (liters) | 217 |
| Engine load | 218 |
| Engine temperature | 219 |
| Axle 1 load | 220 |
| Axle 2 load | 221 |
| Axle 3 load | 222 |
| Axle 4 load | 223 |
| Axle 5 load | 224 |
| Control state flags | 225 |
| Agricultural machinery flags | 226 |
| Harvesting time | 227 |
| Area of harvest | 228 |
| Mowing efficiency | 229 |
| Grain mown volume | 230 |
| Grain moisture | 231 |
| Harvesting drum RPM | 232 |
| Gap under harvesting drum | 233 |
| Security state flags | 234 |
| Tachograph total vehicle distance | 235 |
| Trip distance | 236 |
| Tachograph vehicle speed | 237 |
| Tachograph driver card presence | 238 |
| Driver 1 state | 239 |

| Element name (default SMS Event Text) | ID |
|---------------------------------------|-----|
| LLS Temperature 5 | 260 |

| LVCAN SMS Event | ID |
|-------------------------------------|-----|
| Driver 2 state | 240 |
| Driver 1 continuous driving time | 241 |
| Driver 2 continuous driving time | 242 |
| Driver 1 cumulative break time | 243 |
| Driver 2 cumulative break time | 244 |
| Driver 1 selected activity duration | 245 |
| Driver 2 selected activity duration | 246 |
| Driver 1 cumulative driving time | 247 |
| Driver 2 cumulative driving time | 248 |

RS-485 Interface

RS485 supports only Half Duplex communication. It means that at the same time you can't send/receive Data.

When activated RS485 driver chip draws constant 30mA current.

When Entering Sleep or Deep sleep Chip will be powered off too.

8.8 RS-485 modes

In Configurator's windows select RS232 / RS485 window where is RS485 Settings as shown in Figure 51.

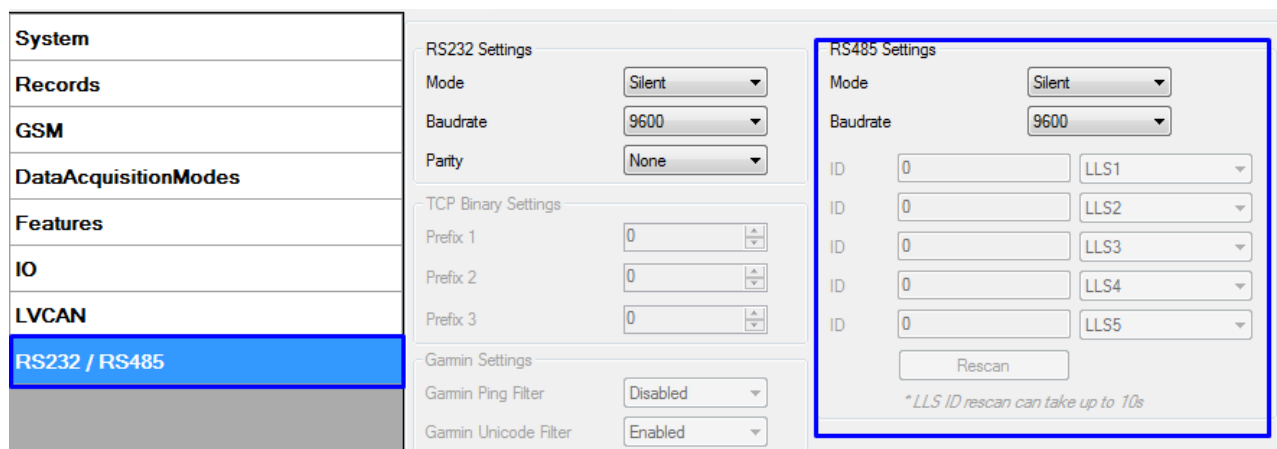


Figure 51 RS-485 settings window

The modes are described below are setting in the configuration window.

8.8.1 RS-485 receive (Silent) mode

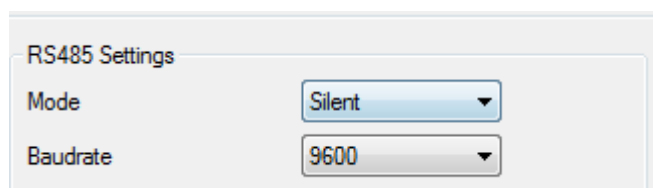
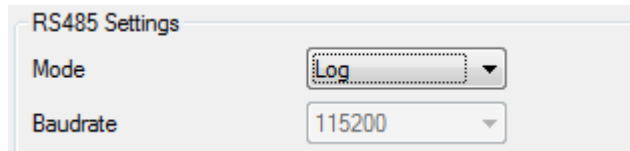


Figure 52 Silent mode

RS485 Works in receive mode. Support debug and testing commands. When command is received answer is sent after that it back up to Receive mode.

8.8.2 RS-485 Transmit (FM log) mode



RS485 Settings

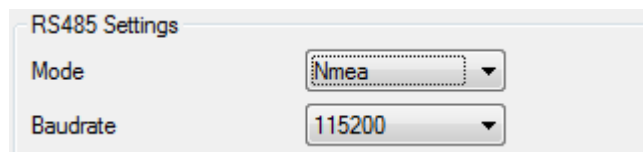
Mode: Log

Baudrate: 115200

Figure 53 Log mode

RS-485 works in transmit mode, it prints FM log. It won't respond to commands

8.8.3 RS-485 Transmit (GPS Nmea) Mode



RS485 Settings

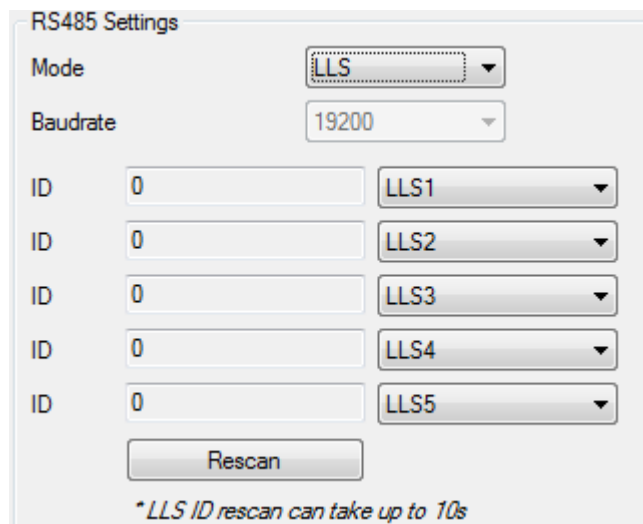
Mode: Nmea

Baudrate: 115200

Figure 54 GPS Nmea mode

RS-485 works in transmit mode, it prints NEMA. It won't respond to commands

8.8.4 RS-485 receive (LLS) mode



RS485 Settings

Mode: LLS

Baudrate: 19200

| | | |
|----|---|------|
| ID | 0 | LLS1 |
| ID | 0 | LLS2 |
| ID | 0 | LLS3 |
| ID | 0 | LLS4 |
| ID | 0 | LLS5 |

Rescan

** LLS ID rescan can take up to 10s*

Figure 55 LLS mode

The mode supports up to five LLS. Baud rate must be 19200. LLS have receiver id.

8.8.5 RS-485 TCP (Ascii, binary) modes



RS485 Settings

Mode: Tcp Ascii

Baudrate: 57600

Figure 56 TCP Ascii mode

In this mode link with external device using text messages can be established.

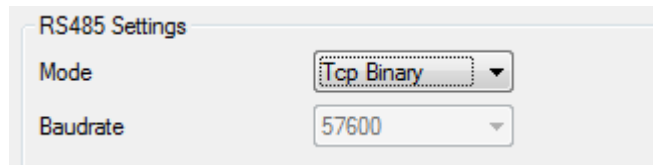


Figure 57 TCP Binary mode

This mode is the same as above but binary messages will be accepted.

8.9 RS-485 Interface

Port connection diagram are shown on the Figure 58:

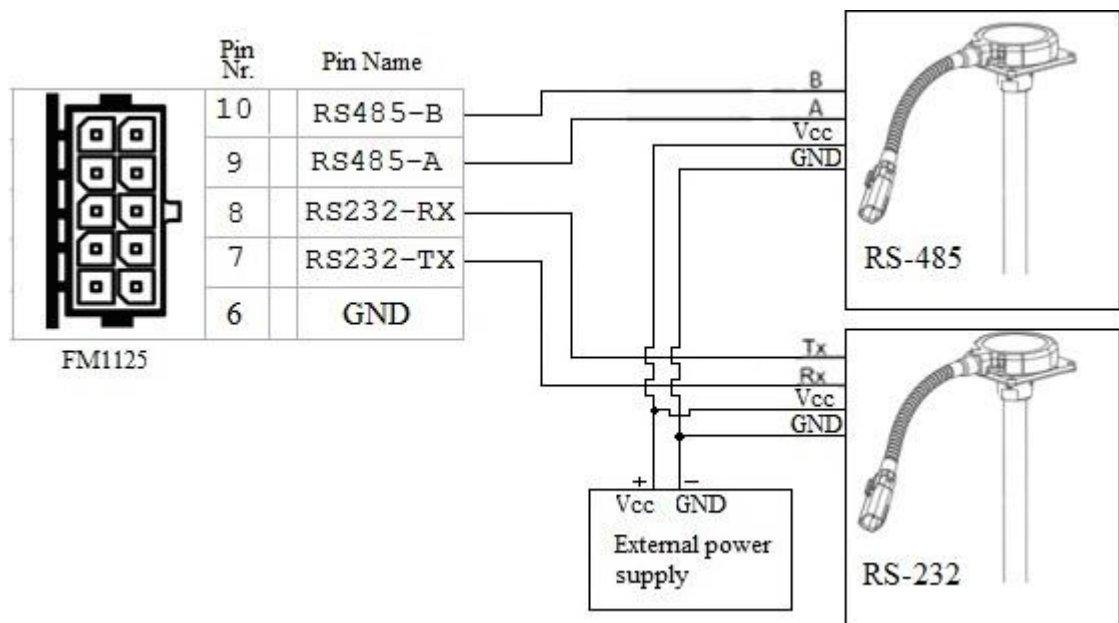


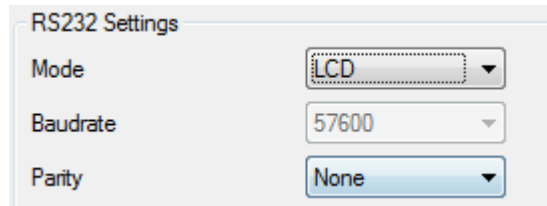
Figure 58 RS-485/232 connection diagram

9 RS-232 Interface

RS-232 supports Full Duplex communication. It means that at the same time you can send/receive Data, because it uses separate lines for transmitting and receiving data.

Most of the modes are the same as RS-485.

9.1.1 RS-232 (LCD) mode



RS232 Settings

Mode: LCD

Baudrate: 57600

Parity: None

Figure 59 LCD mode

In this mode you can communicate with server through terminal. Link between FM and server has to be established for this functionality to work. On valid data Receive Status LED will blink.

9.1.2 RS-232 RFID/RFID M7 modes



RS232 Settings

Mode: RFID

Baudrate: 57600

Parity: None

Figure 60 RFID mode



RS232 Settings

Mode: RFID M7

Baudrate: 9600

Parity: None

Figure 61 RFID M7 mode

The difference between RFID Mode and RFID MF7 Mode is that in RFID Mode FM1125 understands RFID messages that are in hexadecimal format and RFID MF7 Mode understands messages that are in decimal format. For example:

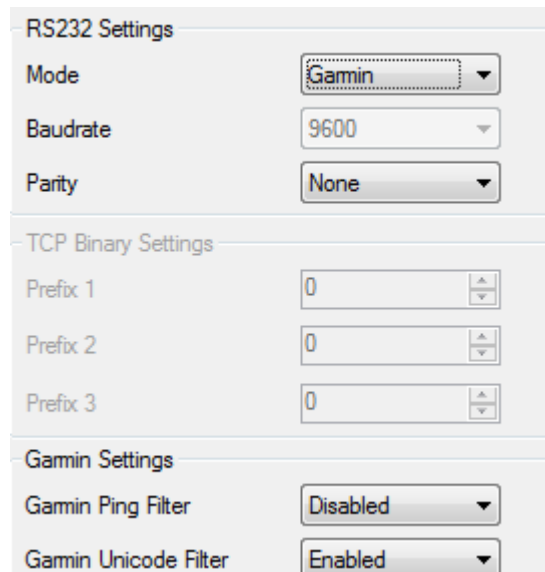
RFID Mode message – “\$aa\$02\$03\$04\$17\$89\$00\$01”

RFID MF7 Mode message – “1213141519”

The chosen mode has to correspond to the RFID reader’s mode. What type of RFID is sent to FM1125 depends on the reader.

For more information about RFID ID’s and devices, please contact to your local sales representative.

9.1.3 RS-232 GARMIN mode



The screenshot shows a configuration window with three sections:

- RS232 Settings:**
 - Mode: Garmin
 - Baudrate: 9600
 - Parity: None
- TCP Binary Settings:**
 - Prefix 1: 0
 - Prefix 2: 0
 - Prefix 3: 0
- Garmin Settings:**
 - Garmin Ping Filter: Disabled
 - Garmin Unicode Filter: Enabled

Figure 62 GARMIN mode

Garmin provides a Fleet Management Interface Tool Kit which connected to FM1125 enables the driver to have a "screen" in their vehicle for real-time navigation, messaging, and job dispatch capabilities to help them be more efficient.

FM1125 and Garmin operational scheme is shown in Figure 63 below:



Figure 63 FM1125+Garmin operational scheme

The following is a list of protocols supported and the corresponding feature/benefit. FM1125 can fully support Fleet Management Interface (FMI) versions up to 2.1. Other or higher versions may be supported, but Teltonika is not responsible for the changes made by Garmin, which may affect the work of FM5500 and Garmin products. For more information about Garmin products and FMI versions, please go to <http://www8.garmin.com/solutions/pnd/supportedproducts.jsp>. Notice that some Garmin products use different connection cables than others.

Standard protocols

Text Message Protocol:

- Allows text messages sent to device to be displayed in "inbox" on unit.
- Garmin can provide confirmation that message was read.
- Garmin can also provide a yes/no box below the text of the message to enable a simple quick response.
- Messages can be up to 199 characters in length.
- Messages can also be generated from device and sent to dispatch/office.
- Messages received will be notified to driver through a pop-up alert on Garmin screen.
- Garmin provides a "virtual keyboard" on device through a touch-screen format for all text communication.

Stop (Destination) Protocol:

- Garmin can display a list of Stops/Jobs reported to the device in a separate icon called "My Stops".
- Driver has ability to navigate directly to Stop from list.
- Garmin can provide status on current Stop in progress.
- Is driver stopped at location?
- How far has Driver progressed through the list of Stops?
- Garmin can also provide confirmation that driver has received a particular Stop, read the details, or deleted it from list.
- Can provide confirmation that a Stop has been completed.

Estimated Time of Arrival Protocol:

- Dispatcher/office can request the ETA of the current stop/job in progress.
- Garmin will notify the actual time of arrival as well as distance remaining to stop.

Auto-Arrival at Stop Protocol:

- This feature is used to tell the Garmin PND to automatically detect that it has arrived at a Stop and then to prompt the driver if they would like to mark the Stop as done and begin navigating to next Stop on the list.
- Auto-arrival can be determined by how long the unit is stopped close to the destination (in the event driver has to park and walk) or by how close the unit needs to be to the destination before the Auto-arrival feature is activated.

Data Deletion Protocol:

- Dispatch/office has the ability to wipe clean the data on the Garmin PND.
- Clean up messages in inbox/remove stops.

Enhanced protocols

Canned Responses/Messages:

- Fleet managers can communicate by sending up to 200 "canned" responses from server to be stored directly on Garmin devices.
- Up to 50 of these canned responses can be utilized for any given scenarios.
- Drivers can store up to 120 canned messages, eliminating the need to type while driving.

Status Protocol:

- Up-to-the-minute communications that allow drivers to automatically send status updates.
- Driver's units can store up to sixteen status indicators such as start/stop shift, on/off break, etc.

Supported features on Tavl client application

Tavl client application lets user to use the following features of GARMIN FMI:

1. Text messaging.
2. Destination message.
3. ETA request.

Text messaging

Text messaging feature lets user to communicate with driver (user that uses Garmin device) by sending text messages via GPRS.

Destination message

Destination message is used to inform a driver of a new destination. When Garmin device receives a destination message from server it displays it as "Stop" to the driver and also gives the driver ability to start navigating to the "Stop" location. New destination in Tavl client is represented as Geozone so new Geozone (as destination) has to be created first.

ETA request message

ETA (Estimated Time of Arrival) request message is used when user wants to know expected arrival time to currently active destination and distance (in meters) from current object location to currently active destination.

10 MOUNTING RECOMMENDATIONS

10.1 Connecting Wires

- Wires should be connected while module is not plugged in.
- Wires should be fastened to the other wires or non-moving parts. Try to avoid heat emitting and moving objects near the wires.
- The connections should not be seen very clearly. If factory isolation was removed while connecting wires, it should be applied again.
- If the wires are placed in the exterior or in places where they can be damaged or exposed to heat, humidity, dirt, etc., additional isolation should be applied.
- Wires cannot be connected to the board computers or control units.

10.2 Connecting Power Source

- Be sure that after the car computer falls asleep, power is still available on chosen wire. Depending on car, this may happen in 5 to 30 minutes period.
- When module is connected, be sure to measure voltage again if it did not decrease.
- It is recommended to connect to the main power cable in the fuse box.

10.3 Connecting Ignition Wire

- Be sure to check if it is a real ignition wire – power does not disappear while starting the engine.
- Check if this is not an ACC wire (when key is in the first position, most electronics of the vehicle are available).
- Check if power is still available when you turn off any of vehicles devices.
- Ignition is connected to the ignition relay output. As alternative, any other relay, which has power output, when ignition is on, may be chosen.

10.4 Connecting Ground Wire

- Ground wire is connected to the vehicle frame or metal parts that are fixed to the frame.
- If the wire is fixed with the bolt, the loop must be connected to the end of the wire.
- For better contact scrub paint from the place where loop is connected.



PAY ATTENTION! Connecting the power supply must be carried out in a very low impedance point on-board vehicle network. These points in the car are the battery terminals. Therefore, we recommend connecting the power of FM1125 (wire GND and POWER) directly to the battery terminals. Another valid option is to connect the wires to the main POWER cable inside the fuse box (if there is none, then to the power supply where the fuses of vehicle's computer are), wire GND must be connected in a special point, designed to connect GND vehicle computer. Connecting the GND at an arbitrary point to the mass of the car is unacceptable, as static and dynamic potentials on the line GND will be unpredictable, which can lead to unstable FM1125 and even its failure.

10.5 Module Installation

- FM1125 must be placed sticker on TOP (please refer picture below).
- It's forbidden to place FM1125 under metal surfaces.
- It's recommended to place FM1125 device far from car radio, speakers or alarm systems.
- FM1125 must be placed so its state is as horizontal as possible.
- FM1125 should not be seen or easily reached.
- FM1125 should be firmly fixed to the surface or cables.
- FM1125 cannot be fixed to heat emitting or moving parts.
- SIM card should be inserted in the module while the connector is plugged off (while module has no power).

It is recommended to place FM1125 device behind dashboard as close to the window as possible. A good example of device placement is displayed in a picture below.

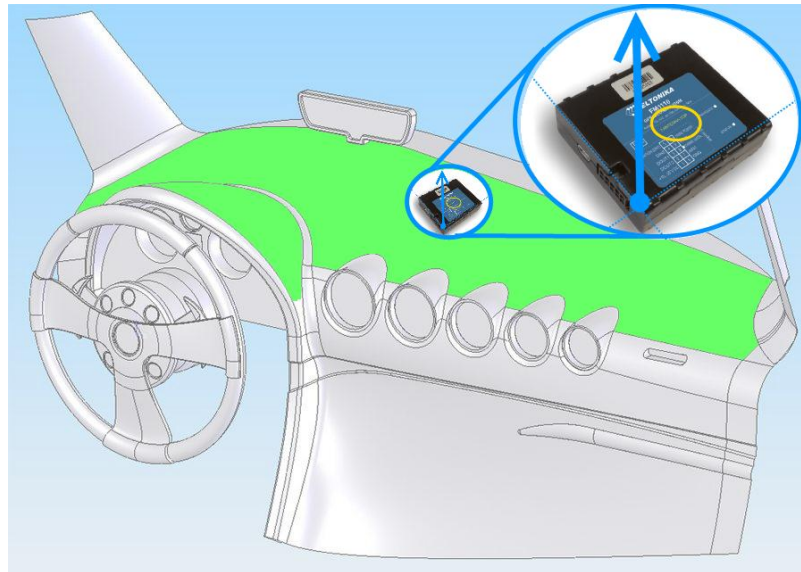


Figure 45 Correct placement of FM1125

11 CHANGE LOG

| Nr. | Date | Version | Comments |
|-----|------------|---------|--|
| 1 | 2015-08-25 | 1.0 | Preliminary draft release. |
| 2 | 2015-08-26 | 1.1 | Added photo in page 1, fixed info |
| 3 | 2015-08-26 | 1.2 | Added overvoltage protection info, fixed SMS event ID's, added info about device external/internal antennas. |
| 4 | 2015-09-03 | 1.3 | Fixed 1 - wire connection (normal to parasite power). Redrawn image of RS232/RS485 connection to FM and external data source ; Added explanation of connection between FM1125 and RS-232/RS-485 |
| 5 | 2015-09-22 | 1.4 | Changed temp sensor connection scheme |
| 6 | 2015-10-09 | 1.5 | Changed flash memory size |
| 7 | 2016-01-25 | 1.6 | Corrected GSM parameter IDs (pages 58 - 61); Corrected I/O element parameter IDs (pages 73 - 74) Corrected RS232 and RS485 parameter IDs, page 77; Corrected tables with parameter IDs for I/O events and SMS events configuration (pages 75 - 79); |